

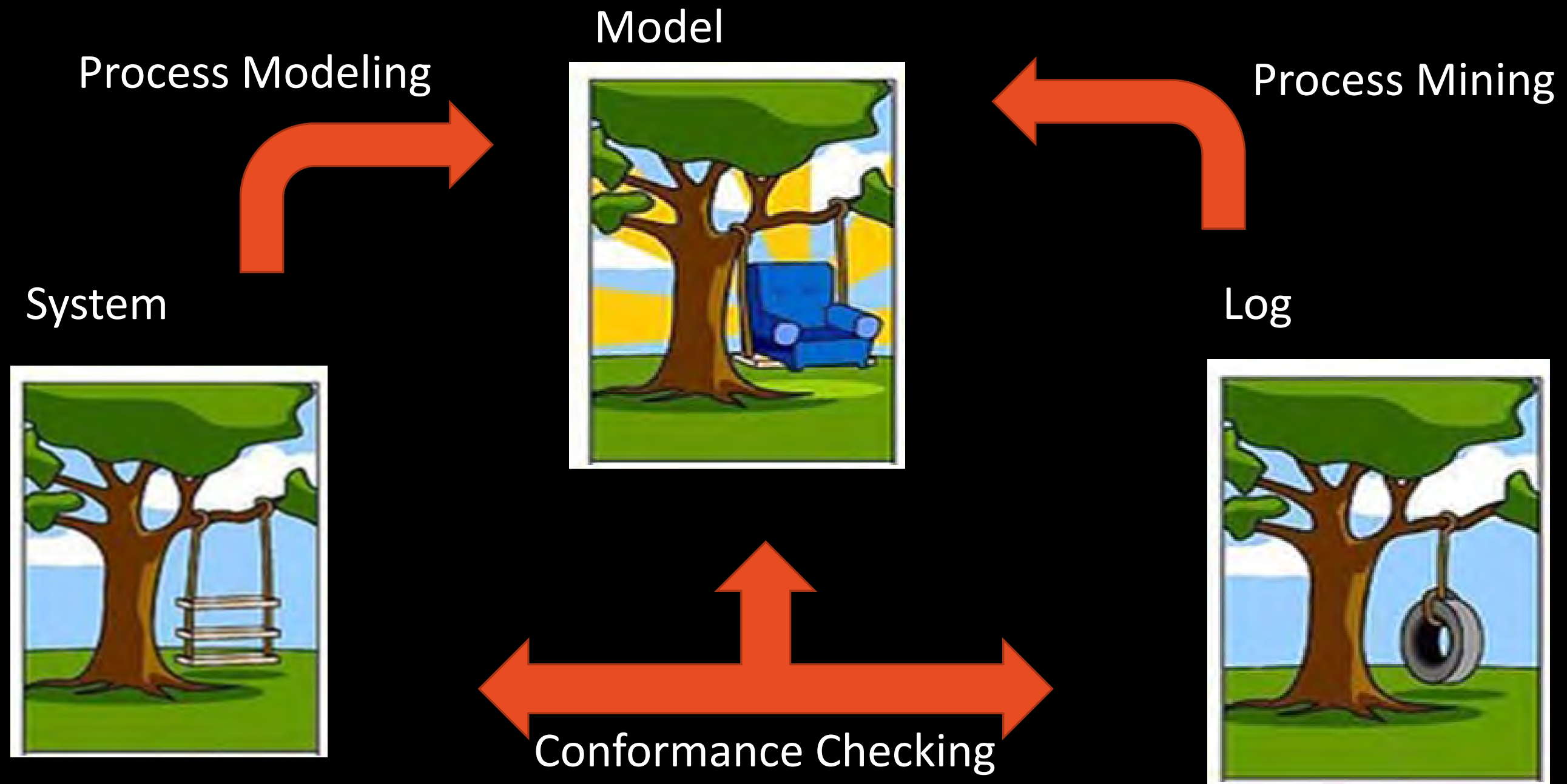
A Unified Approach for Measuring Precision and Generalization Based on Anti-Alignments

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Conformance in Process Mining



Alignments & Fitness

- *Fitness* is a measure for the amount of behavior shown in the log that fits the model
- Alignments provide the basis for computing fitness
- An *alignment* shows where deviations occurred and why these deviation are considered as such

Model



Log



Anti-Alignments

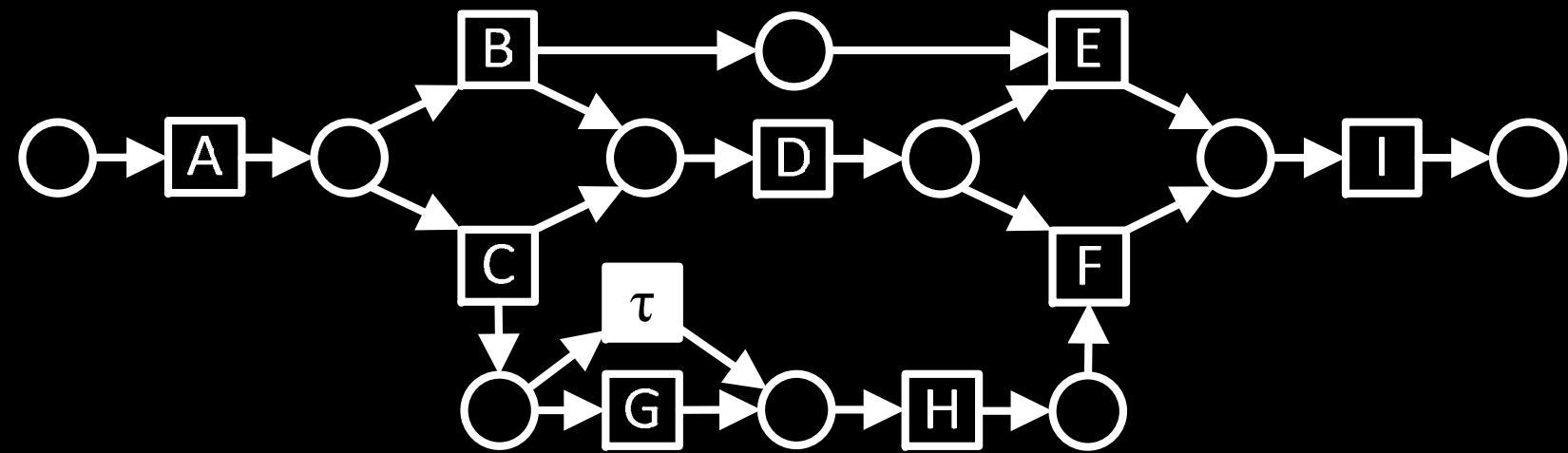
- Anti-alignments show how far the model allows you to deviate from observed behavior
- Given a model M , a finite log L and a distance function d , an (n, m) anti-alignment is a firing sequence s of the model of length n , such that for each trace t in the log holds that $d(s, t) \geq m$



Anti-Alignments - basics

- Given a model M , a finite log L and a distance function d , an (n,m) anti-alignment is a firing sequence s of the model of length n , such that for each trace t in the log holds that $d(s,t) \geq m$
- A maximal complete anti alignment of length n reaches the final marking and maximizes the distance m .

Trace	Frequency
$\langle A, B, D, E, I \rangle$	1207
$\langle A, C, D, G, H, F, I \rangle$	145
$\langle A, C, G, D, H, F, I \rangle$	56
$\langle A, C, H, D, F, I \rangle$	23
$\langle A, C, D, H, F, I \rangle$	28



Maximal complete AA: $\langle A, C, G, H, D, F, I \rangle$ with $n=7$ and $m=1/7$

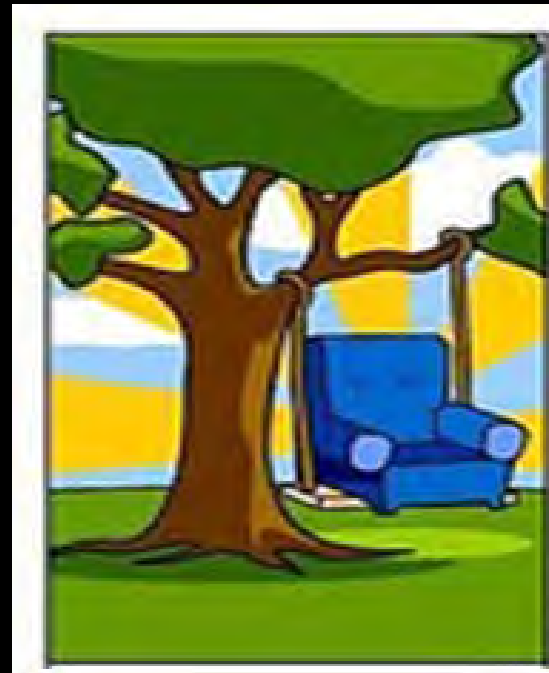
Anti-Alignments - properties

- No anti alignments have to exist, if L is the language of M
- If M has a loop, infinitely many anti-alignments exist and their distances typically go to 1.
- Finding an anti-alignment with maximal m , given n can be translated into a SAT problem (when using hamming distances)
- Finding an anti-alignment with minimal n , given m can be translated into a SAT problem (when using hamming distances)
- *No smart way exists yet for computing anti-alignments using edit-distances.*

Conformance Checking: Precision

- Precision is a measure for the fraction of the behavior of the model that is not in the log
- Simply comparing the (possibly infinite) behavior is infeasible and not very informative.
- Most precision metrics estimate the size of the “unseen” behavior by looking “one step ahead”.

Model

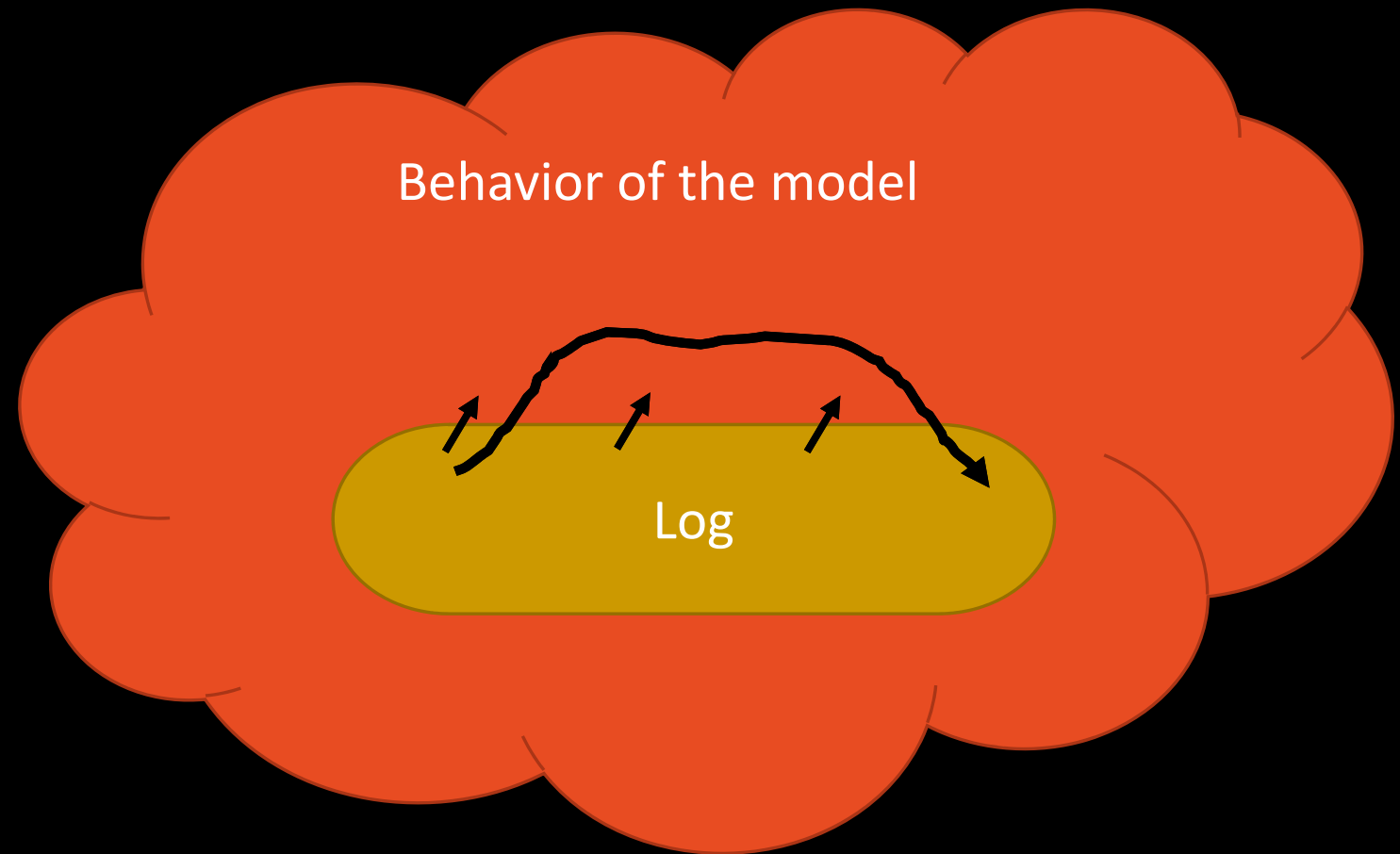


Log



Anti-Alignment Based Precision

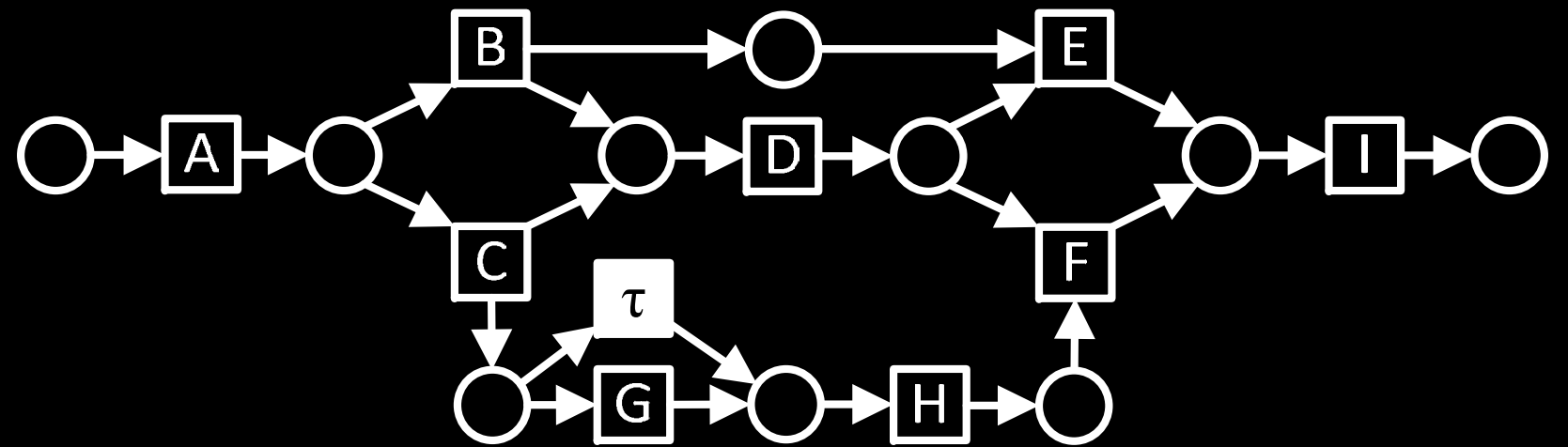
- Anti-alignments show behavior of the model as different as possible from behavior in the log
- With anti-alignments, you look at entire paths!



Anti-Alignment Based Precision

- Consider a model M and a log L .
- Now remove a trace t from the log to get L^t .
- Compute a maximal complete anti alignment s of length $|t|$ for log L^t .
- In a very precise model, $s = t$, hence $1-d(s,t)$ is a precision measure.

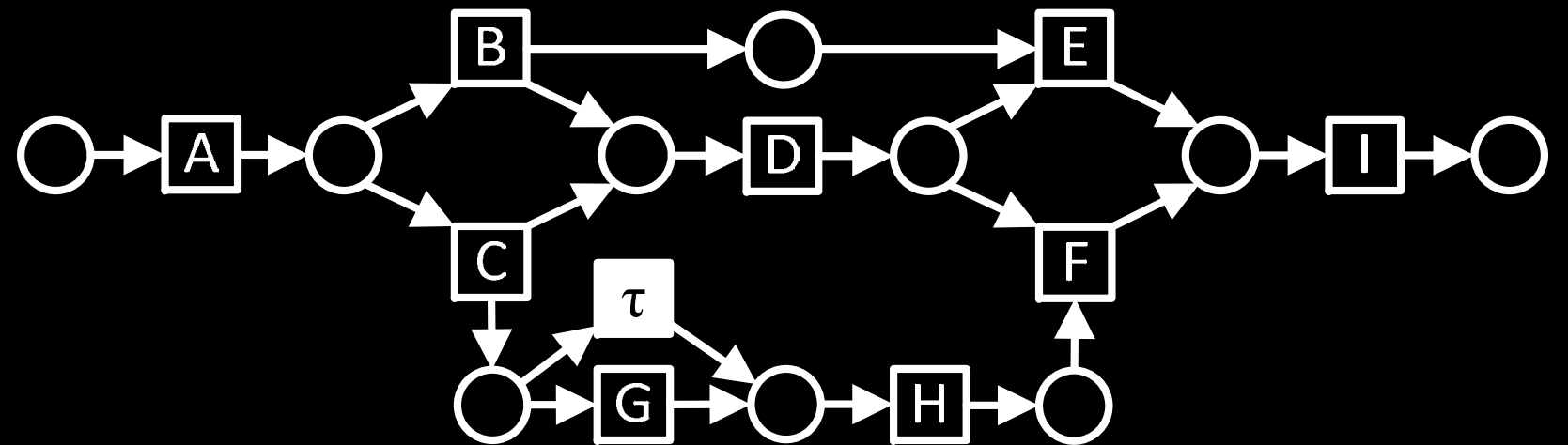
Trace t	Freq.	AA for $L^t (s)$	$d(s,t)$
$\langle A,B,D,E,I \rangle$	1207		
$\langle A,C,D,G,H,F,I \rangle$	145		
$\langle A,C,G,D,H,F,I \rangle$	56		
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$\langle A,C,D,H,F,I \rangle$	28		



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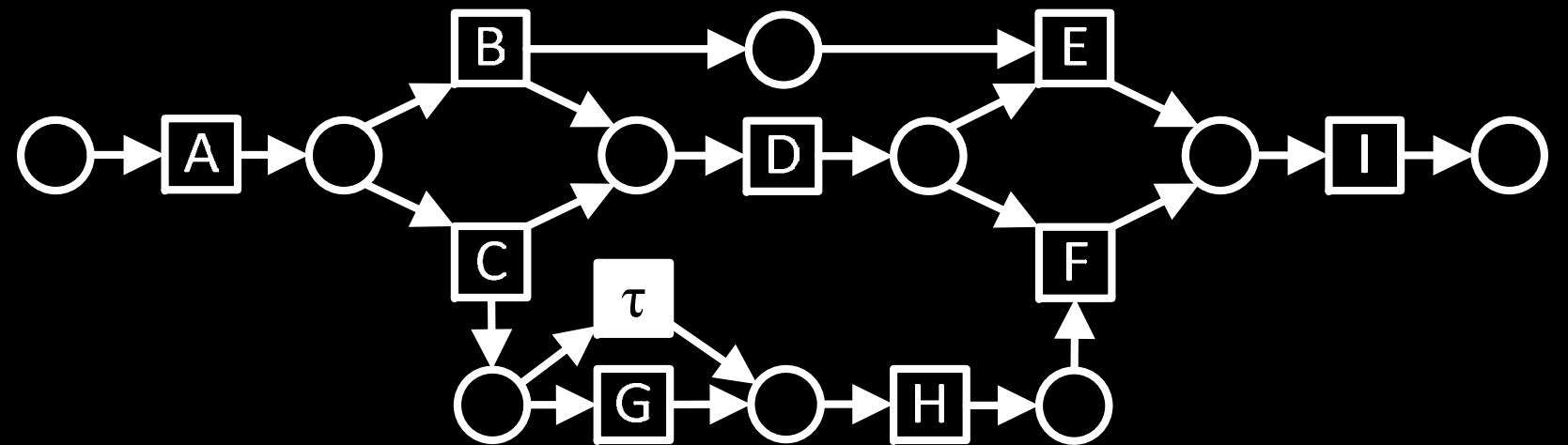
Trace t	Freq.	AA for $L^t (s)$	$d(s,t)$
$\langle A,B,D,E,I \rangle$	1207	$\langle A,B,D,E,I \rangle$	0
$\langle A,C,D,G,H,F,I \rangle$	145		
$\langle A,C,G,D,H,F,I \rangle$	56		
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$\langle A,C,D,H,F,I \rangle$	28		



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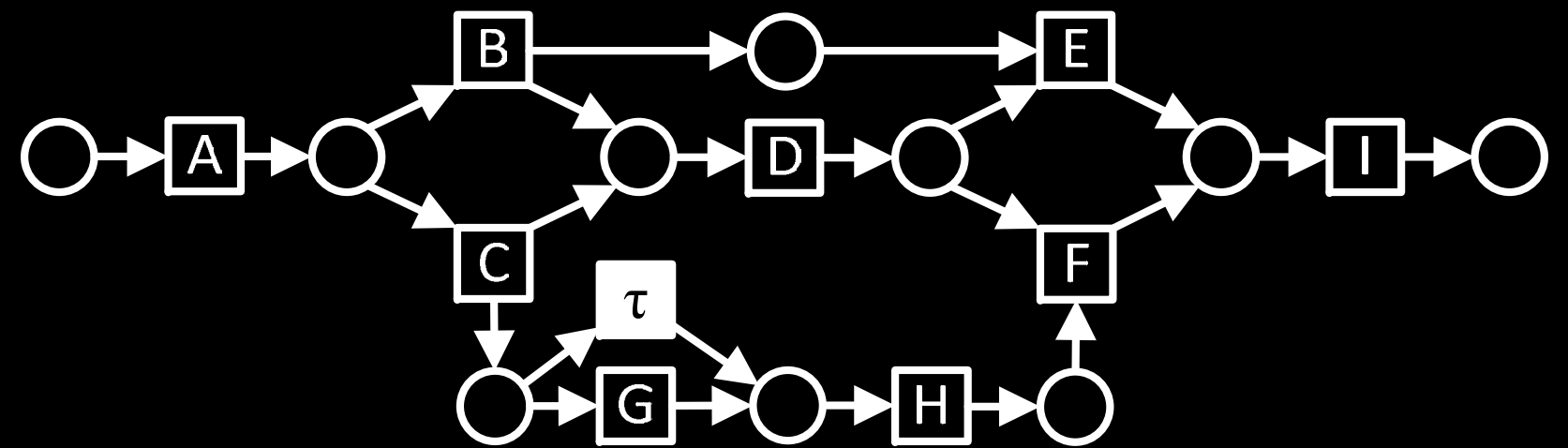
Trace t	Freq.	AA for $L^t (s)$	$d(s,t)$
$\langle A,B,D,E,I \rangle$	1207	$\langle A,B,D,E,I \rangle$	0
$\langle A,C,D,G,H,F,I \rangle$	145	$\langle A,C,G,H,D,F,I \rangle$	$2/7$
$\langle A,C,G,D,H,F,I \rangle$	56		
$\langle A,C,H,D,F,I \rangle$	23		
$\langle A,C,D,H,F,I \rangle$	28		



Anti-Alignment Based Precision (trace based)

- Consider a model M and a log L .
- Now remove a trace t from the log to get L^t .
- Compute a maximal complete anti alignment s of length $|t|$ for log L^t .
- In a very precise model, $s = t$, hence $1-d(s,t)$ is a precision measure.

Trace t	Freq.	AA for $L^t : s$	$d(s,t)$
$\langle A,B,D,E,I \rangle$	1207	$\langle A,B,D,E,I \rangle$	0
$\langle A,C,D,G,H,F,I \rangle$	145	$\langle A,C,G,H,D,F,I \rangle$	$2/7$
$\langle A,C,G,D,H,F,I \rangle$	56	$\langle A,C,G,H,D,F,I \rangle$	$2/7$
$\langle A,C,H,D,F,I \rangle$	23	$\langle A,C,H,D,F,I \rangle$	0
$\langle A,C,D,H,F,I \rangle$	28	$\langle A,C,D,H,F,I \rangle$	0

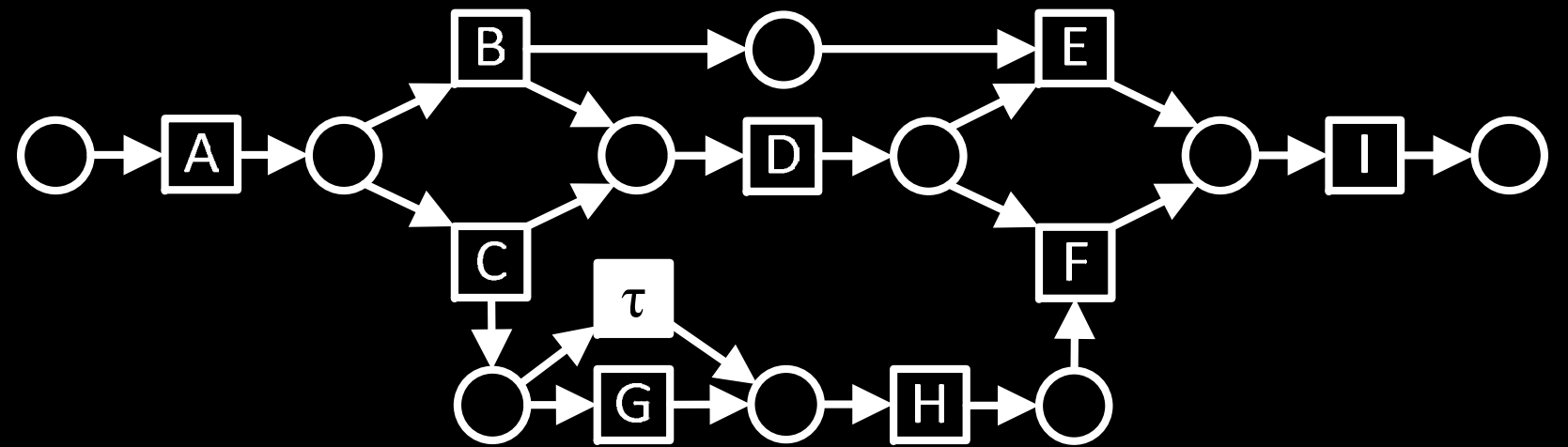


$$\text{Precision } P_t = (1+5/7+5/7+1+1)/5 = 0.886$$

Anti-Alignment Based Precision (log based)

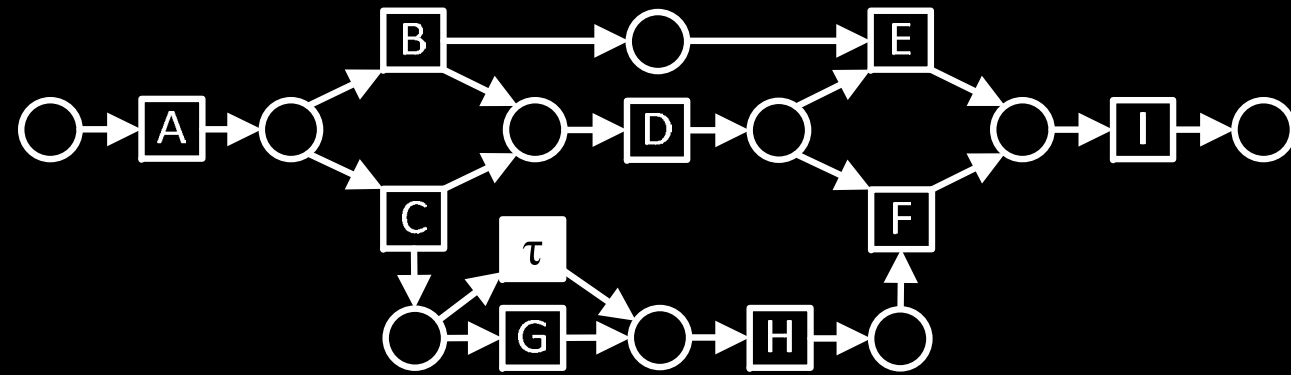
- Consider a model M and a log L .
- Compute a maximal complete anti alignment s of length $x \cdot |t|^{mx}$ for log L .
- In a very precise model, $s \in L$ and hence the minimal $d(s,t)$ will be 0.

Trace t	Freq.	AA for $L^t : s$	$d(s,t)$
$\langle A,B,D,E,I \rangle$	1207	$\langle A,B,D,E,I \rangle$	0
$\langle A,C,D,G,H,F,I \rangle$	145	$\langle A,C,G,H,D,F,I \rangle$	$2/7$
$\langle A,C,G,D,H,F,I \rangle$	56	$\langle A,C,G,H,D,F,I \rangle$	$2/7$
$\langle A,C,H,D,F,I \rangle$	23	$\langle A,C,H,D,F,I \rangle$	0
$\langle A,C,D,H,F,I \rangle$	28	$\langle A,C,D,H,F,I \rangle$	0
-	-	$\langle A,C,G,H,D,F,I \rangle$	$1/7$

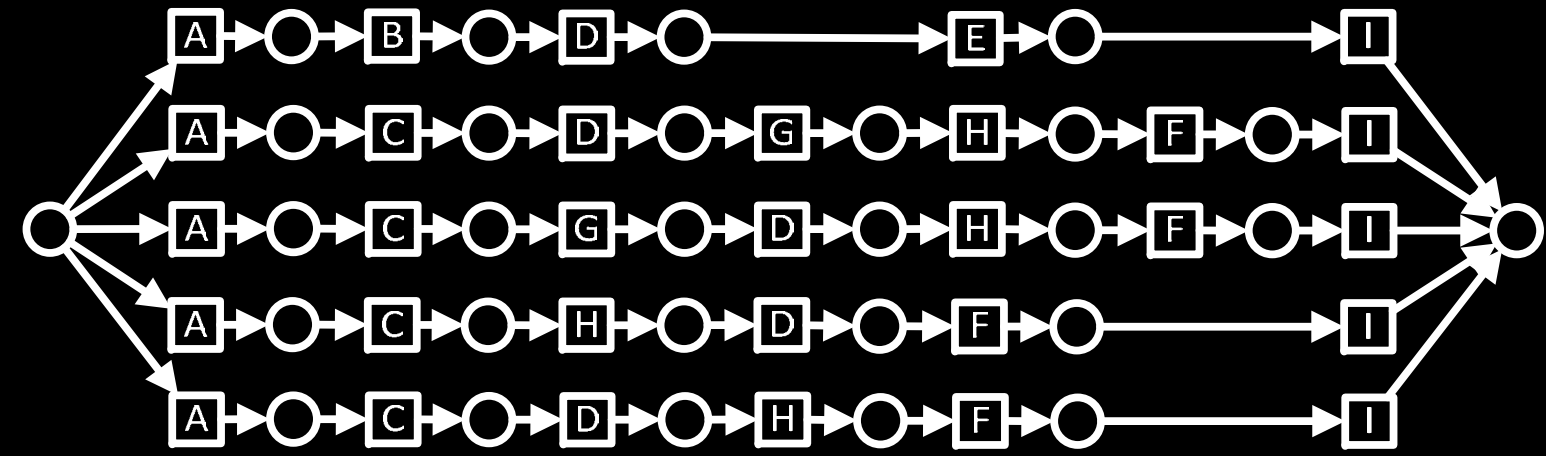


Precision $P_1^2 = 1 - 1/7 = 0.857$

Precision

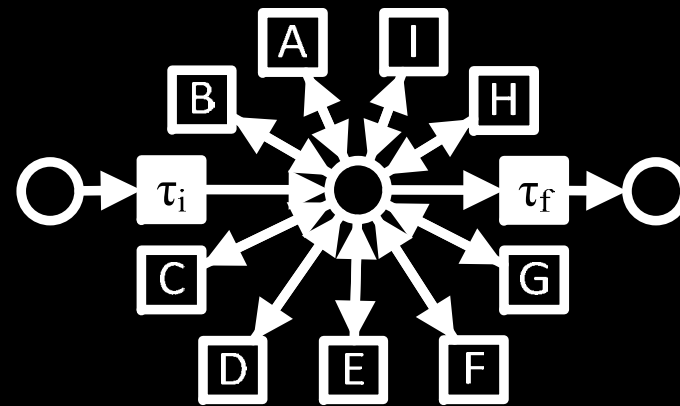


$$P_{ETC} = 0.994, P_a = 0.982, P_t = 0.886, P_l = 0.857$$



$$P_{ETC} = 0.359, P_a = 1, P_t = 1, P_l = 1$$

Trace	Frequency
<A,B,D,E,I>	1207
<A,C,D,G,H,F,I>	145
<A,C,G,D,H,F,I>	56
<A,C,H,D,F,I>	23
<A,C,D,H,F,I>	28



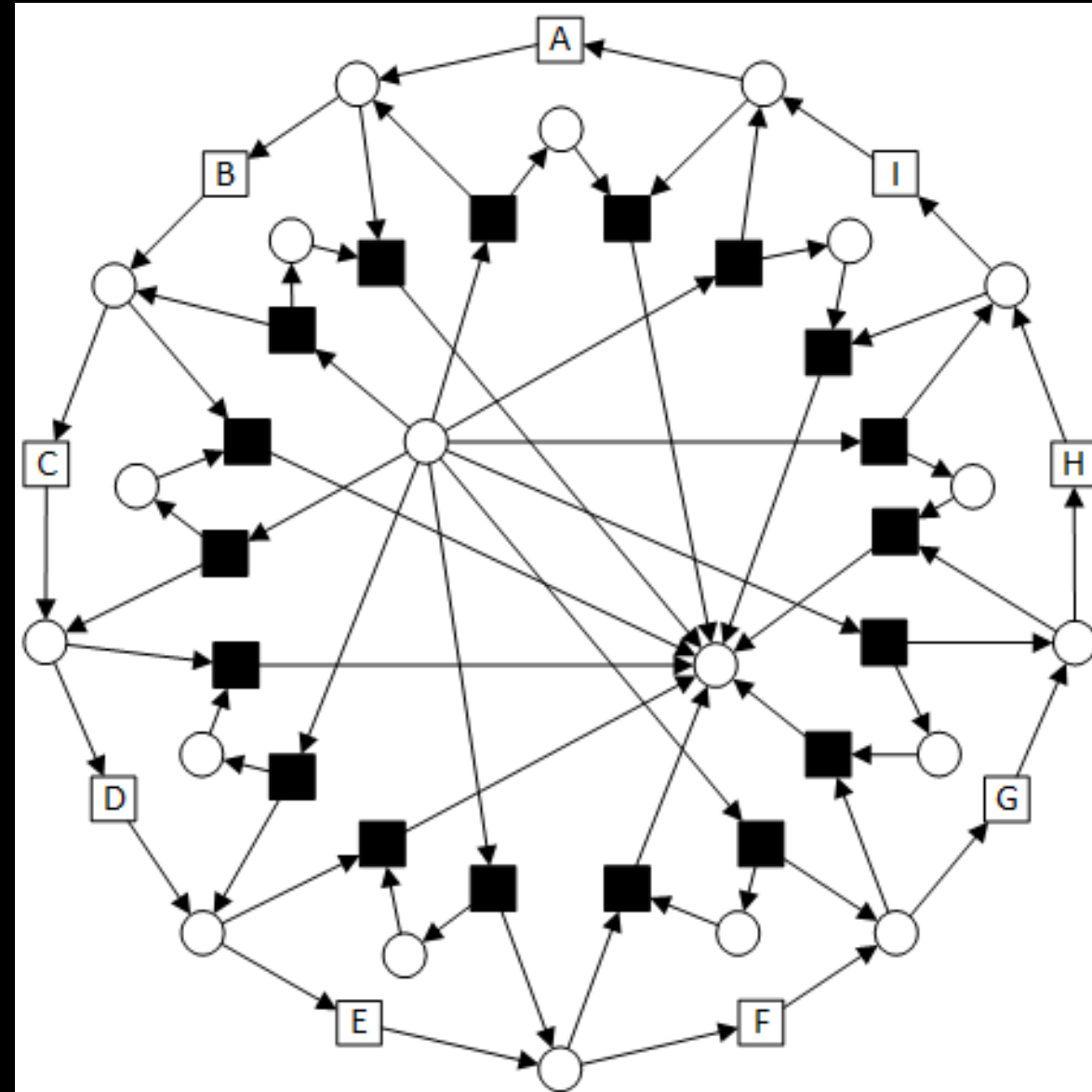
$$P_{ETC} = 0.119, P_a = 0.142, P_t = 0, P_l = 0$$



$$P_{ETC} = 1, P_a = 1, P_t = 1, P_l = 1$$

Precision

Trace	Frequency
$\langle A, B, D, E, I \rangle$	1207
$\langle A, C, D, G, H, F, I \rangle$	145
$\langle A, C, G, D, H, F, I \rangle$	56
$\langle A, C, H, D, F, I \rangle$	23
$\langle A, C, D, H, F, I \rangle$	28

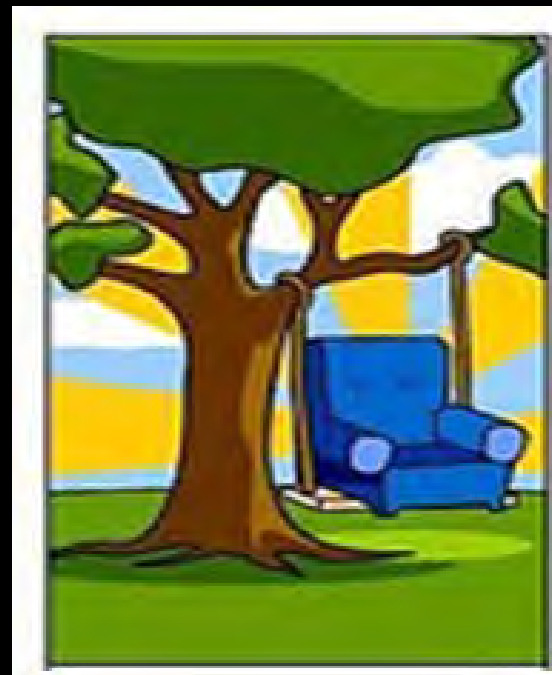


$$P_{ETC} = 0.185, P_a = 0.889, P_t = 0, P_l = 0$$

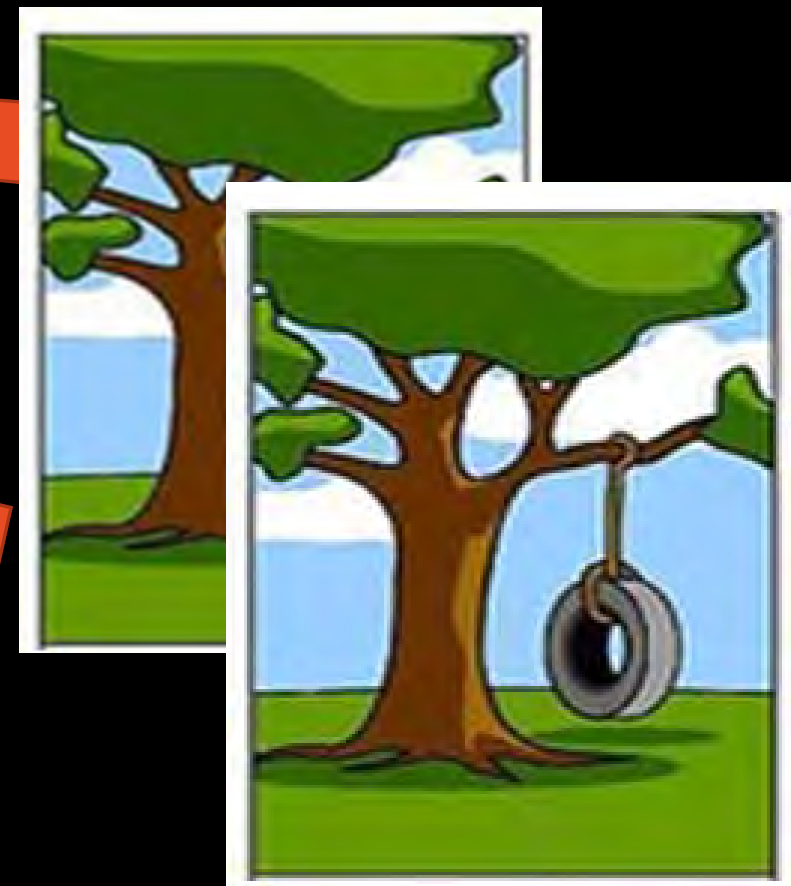
Conformance Checking: Generalization

- Generalization is a measure for the ability of a model to predict unseen, but correct behavior
- Behavior is correct if it is part of the unknown system
- Most generalization metrics look at frequencies of model elements

Model

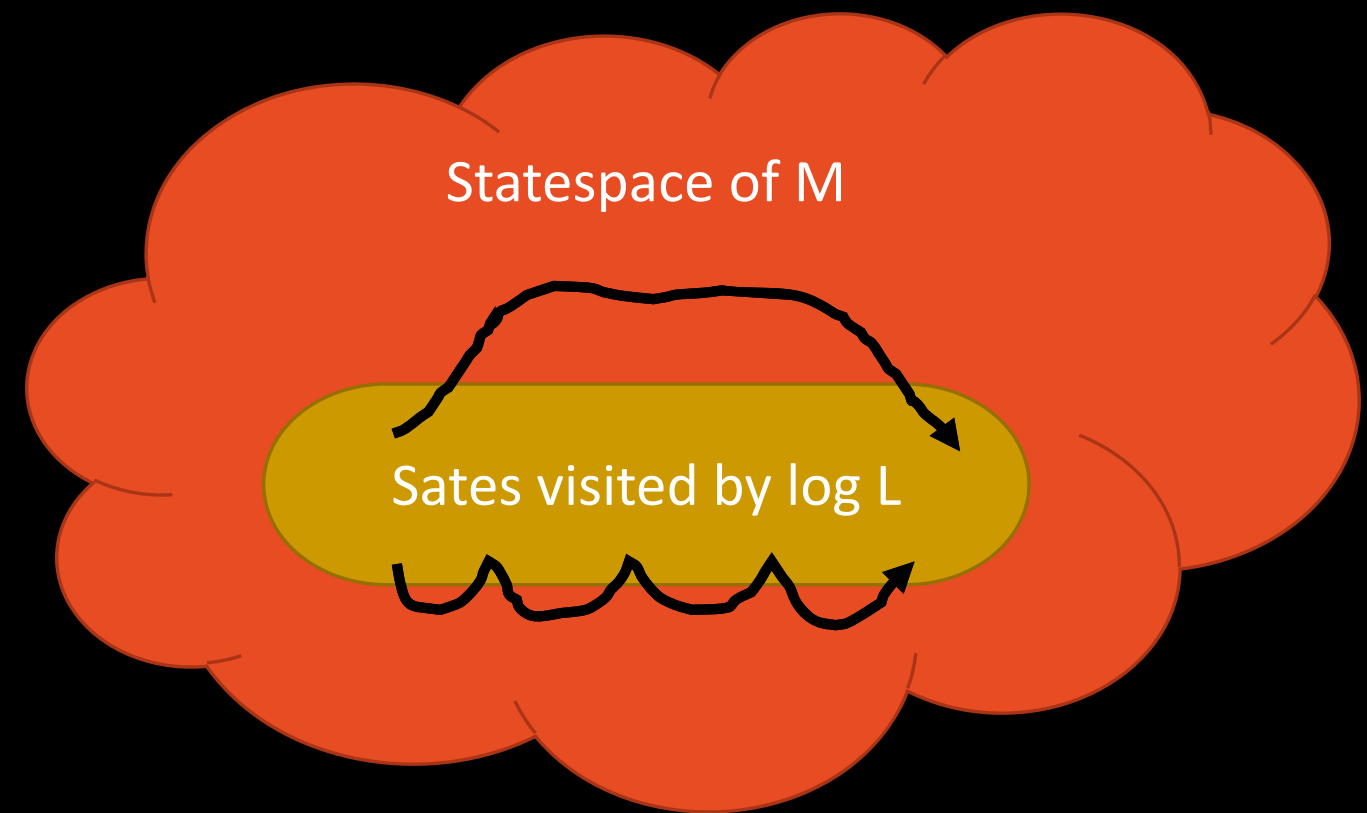


System



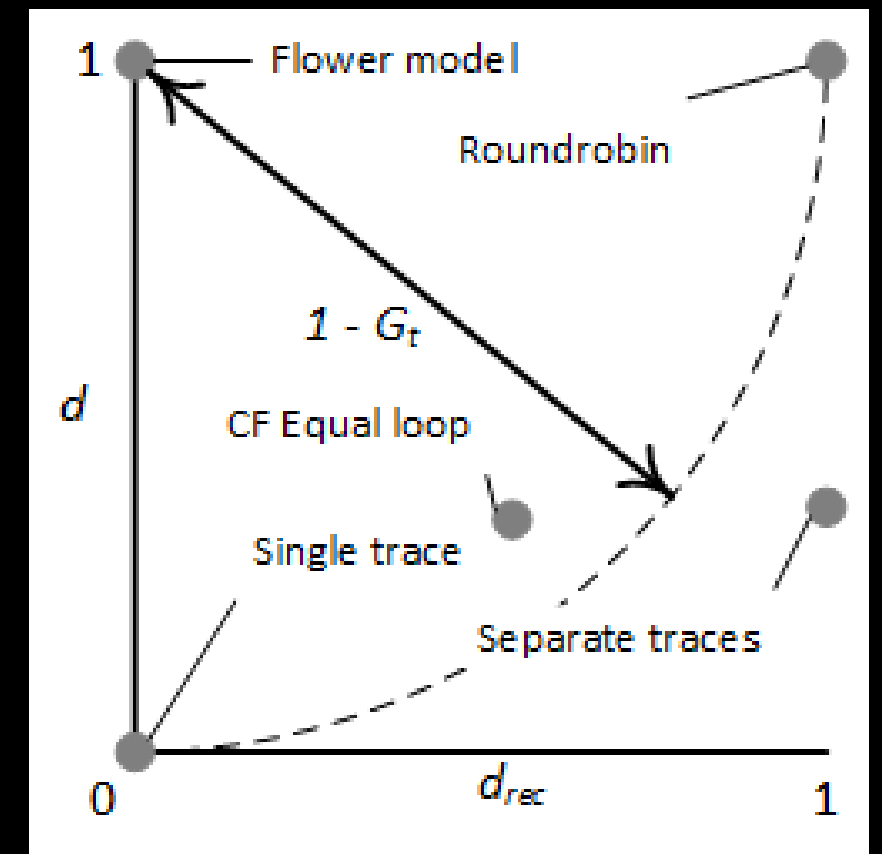
Generalization

- Assumption: A model generalizes if it allows for new sequences of behavior while not introducing too many new states.
- Again, we use anti-alignments!
- Recovery distance is a measure for the maximal number of steps to get from the anti-alignment back into the statespace covered by the log.



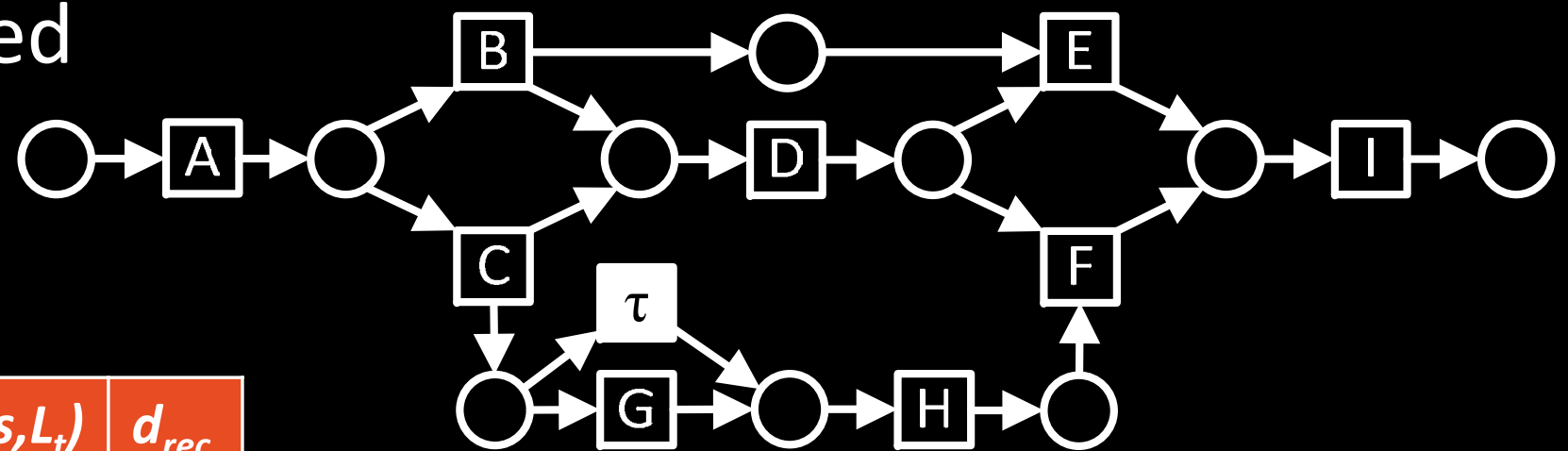
Anti-Alignment Based Generalization

- Consider a model M and a log L
- Now remove a trace t from the log to get L^t and compute the corresponding anti-alignment s
- A model generalizes if s is very different from the traces in L^t is high, and the recovery distance is low



Anti-Alignment Based Generalization

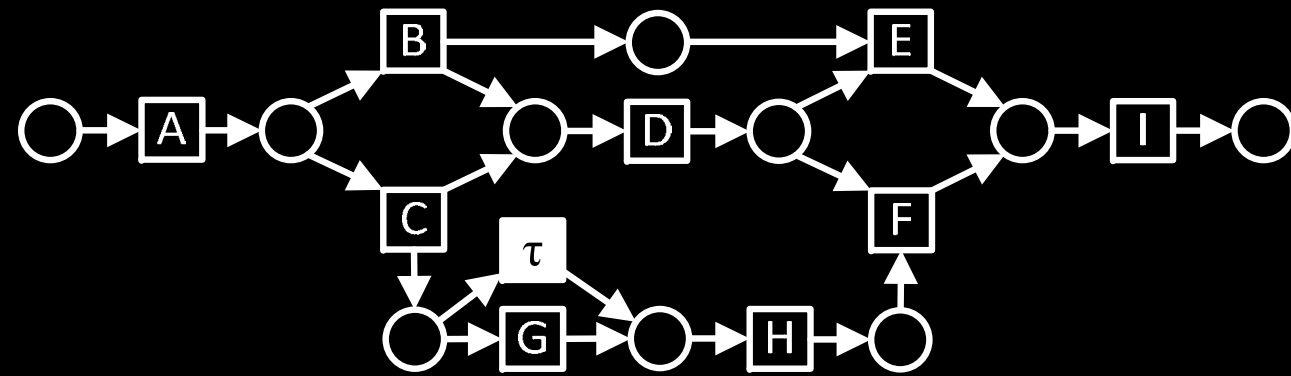
- Same procedure is used as for precision
- Distance to the log L^t is considered
- Recovery distance is considered
- Trace frequency is considered!



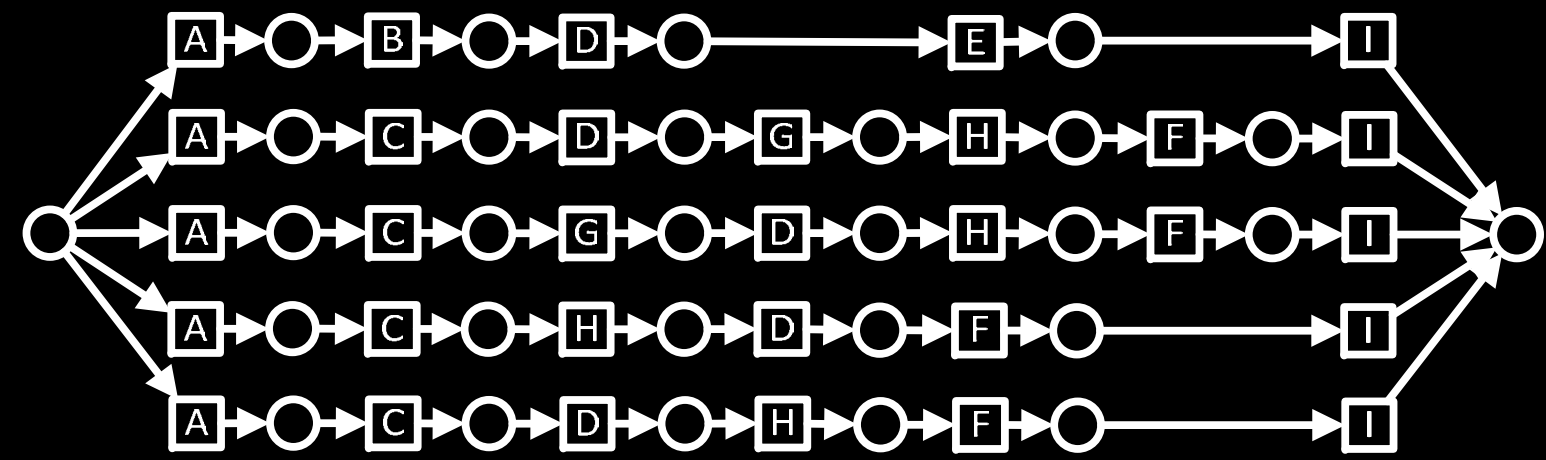
Precision $P_t = 0.886$
 Precision $P_l = 0.857$
 Generalization $G_t = 0.270$
 Generalization $G_l = 0.143$

Trace t	Freq.	AA for $L^t : s$	$d(s,t)$	$d(s,L_t)$	d_{rec}
$\langle A,B,D,E,I \rangle$	1207	$\langle A,B,D,E,I \rangle$	0	$3/6$	$2/4$
$\langle A,C,D,G,H,F,I \rangle$	145	$\langle A,C,G,H,D,F,I \rangle$	$2/7$	$1/7$	0
$\langle A,C,G,D,H,F,I \rangle$	56	$\langle A,C,G,H,D,F,I \rangle$	$2/7$	$1/7$	0
$\langle A,C,H,D,F,I \rangle$	23	$\langle A,C,H,D,F,I \rangle$	0	$2/6$	$1/6$
$\langle A,C,D,H,F,I \rangle$	28	$\langle A,C,D,H,F,I \rangle$	0	$1/6$	0
-	-	$\langle A,C,G,H,D,F,I \rangle$		$1/7$	0

Generalization

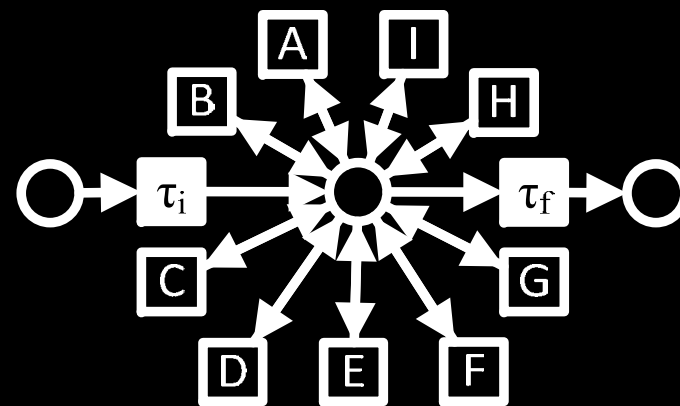


$$G = 0.585, G_t = 0.270, G_l = 0.143$$



$$G_a = 0.145, G_t = 0, G_l = 0$$

Trace	Frequency
<A,B,D,E,I>	1207
<A,C,D,G,H,F,I>	145
<A,C,G,D,H,F,I>	56
<A,C,H,D,F,I>	23
<A,C,D,H,F,I>	28



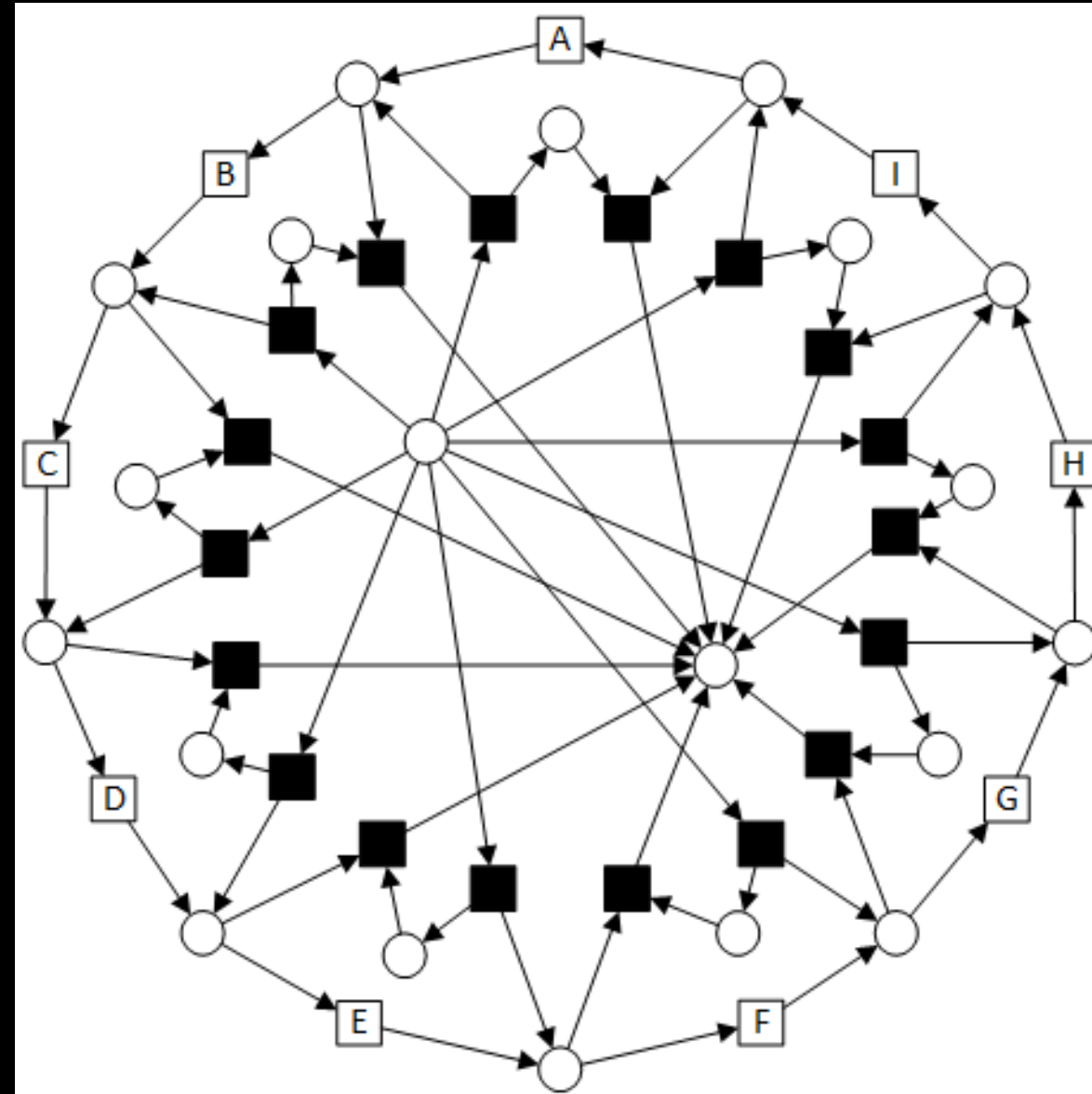
$$G_a = 0.903, G_t = 1, G_l = 1$$



$$G_a = 0.900, G_t = 0, G_l = 0$$

Generalization

Trace	Frequency
$\langle A, B, D, E, I \rangle$	1207
$\langle A, C, D, G, H, F, I \rangle$	145
$\langle A, C, G, D, H, F, I \rangle$	56
$\langle A, C, H, D, F, I \rangle$	23
$\langle A, C, D, H, F, I \rangle$	28



$$G_a = 0.4, G_t = 0, G_l = 0$$

Conclusions & Future Work

- Anti-alignments provide insights into the behavior of a model outside of the log
- Using anti-alignments, we provide metrics for precision and generalization
- Our precision metric consistently ranks models with more traces as less precise as opposed to other metrics
- Efficient implementations are underway:
 - For various distance functions (hamming, edit, etc.)
 - For various model types (Petri nets / process trees)

