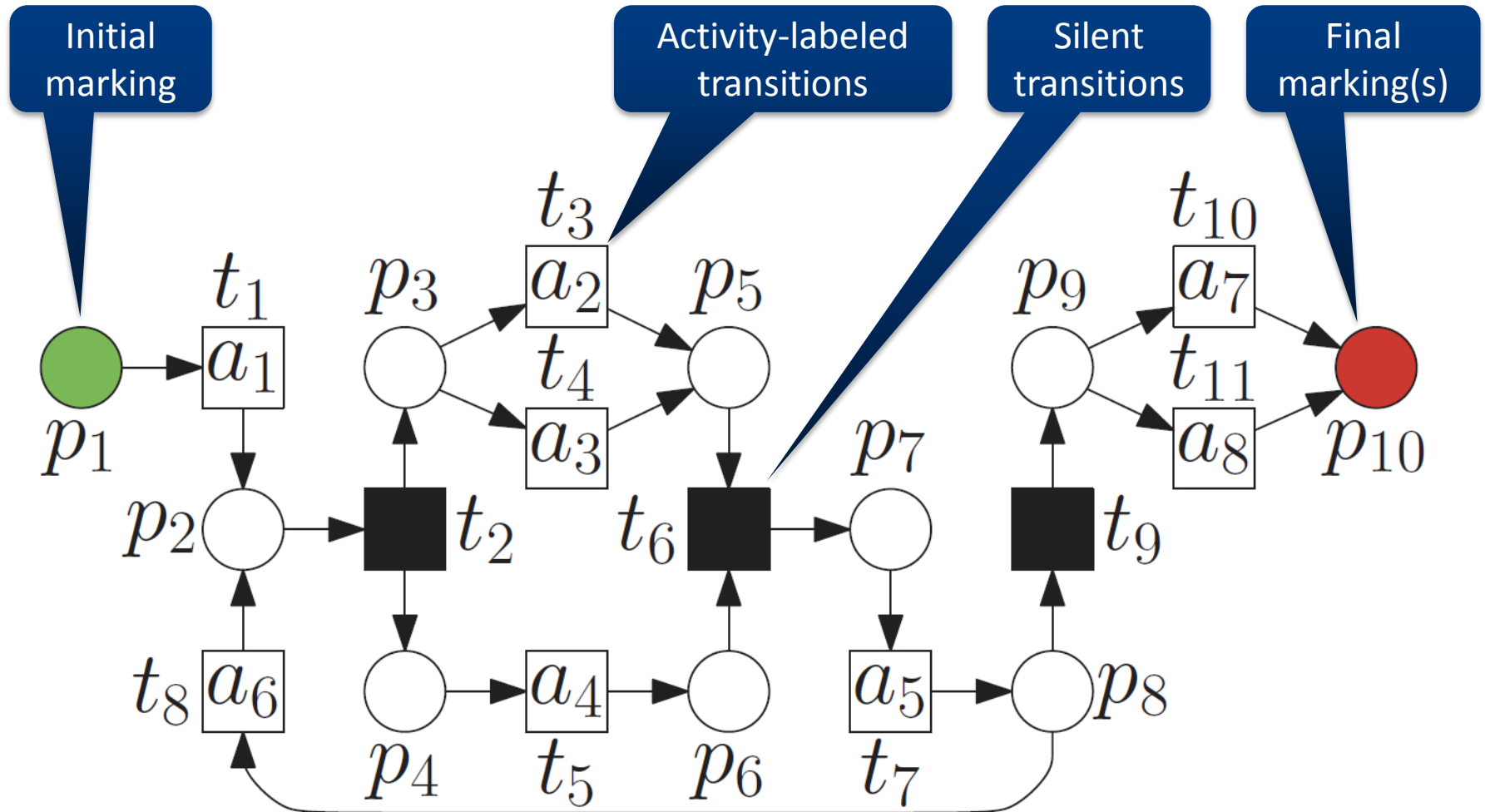


Eric Verbeek

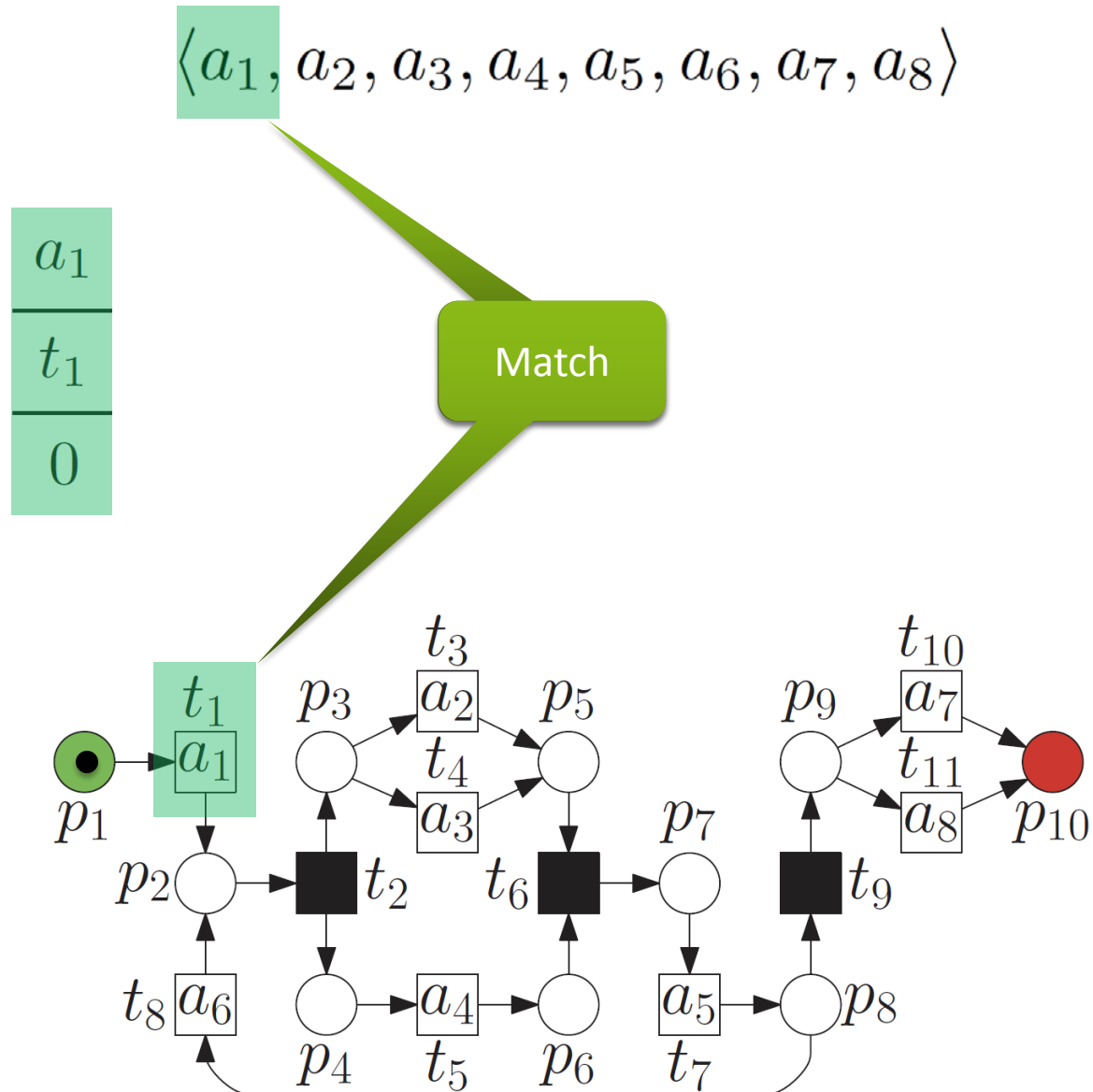
Decomposed Replay Using Hiding and Reduction

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 - Decomposed replay
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 - Problem with decomposed replay
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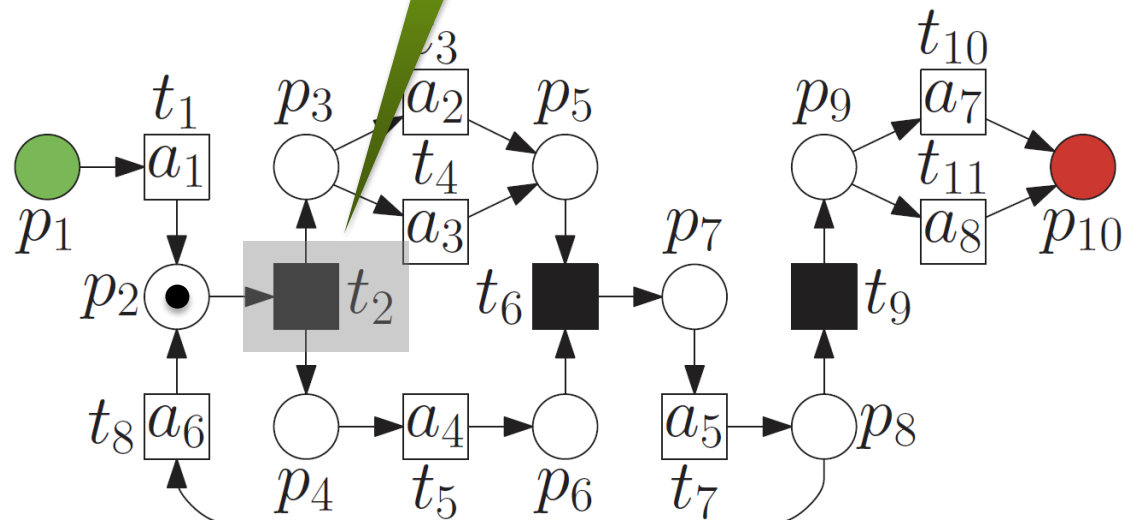


$$\langle a_1, a_2, a_3, a_4, a_5, a_6, a_7, a_8 \rangle$$



$$\langle a_1, a_2, a_3, a_4, a_5, a_6, a_7, a_8 \rangle$$

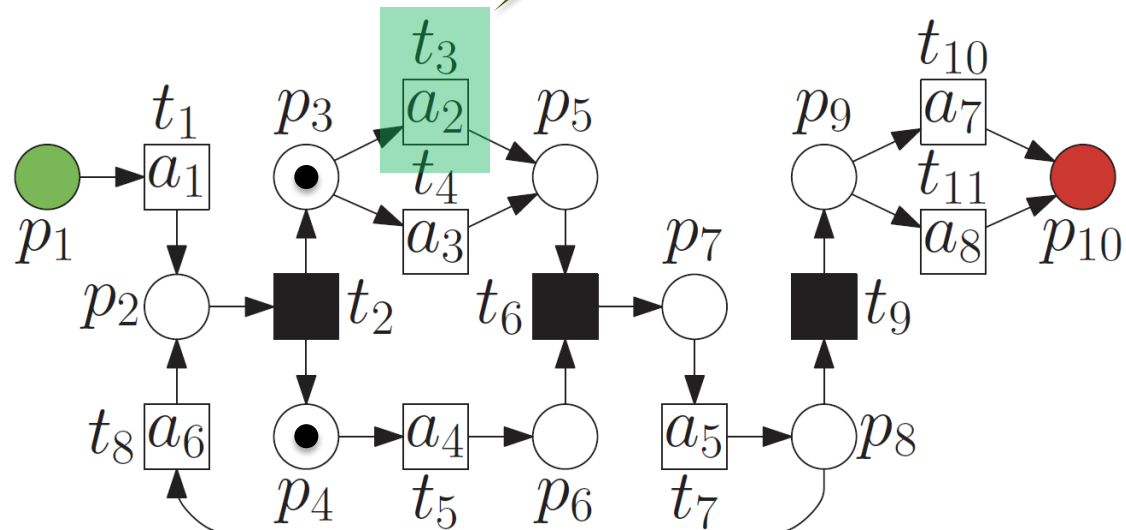
a_1	τ
t_1	t_2
0	0



$\langle a_1, a_2, a_3, a_4, a_5, a_6, a_7, a_8 \rangle$

a_1	τ	a_2
t_1	t_2	t_3
0	0	0

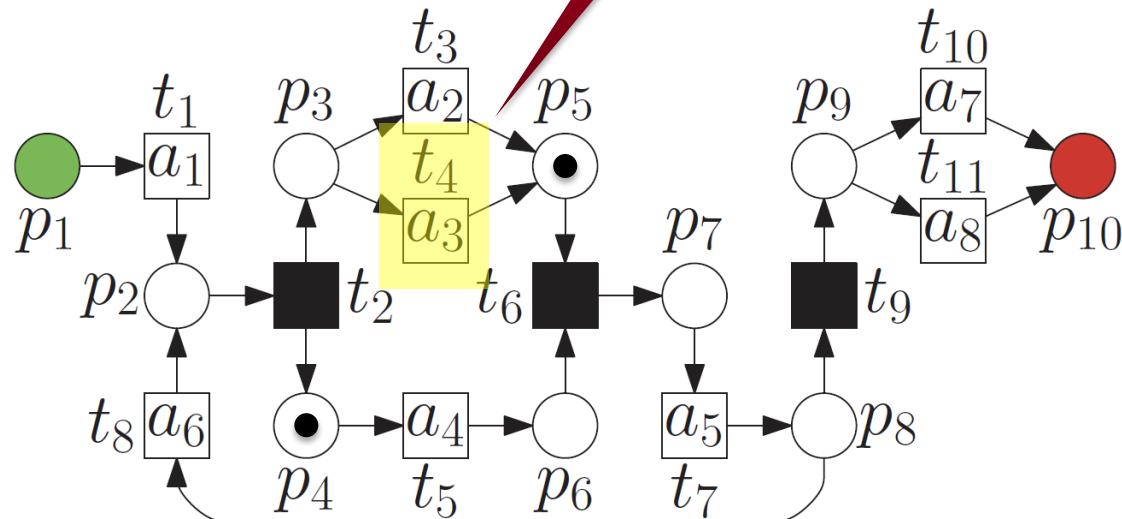
Match



$\langle a_1, a_2, a_3, a_4, a_5, a_6, a_7, a_8 \rangle$

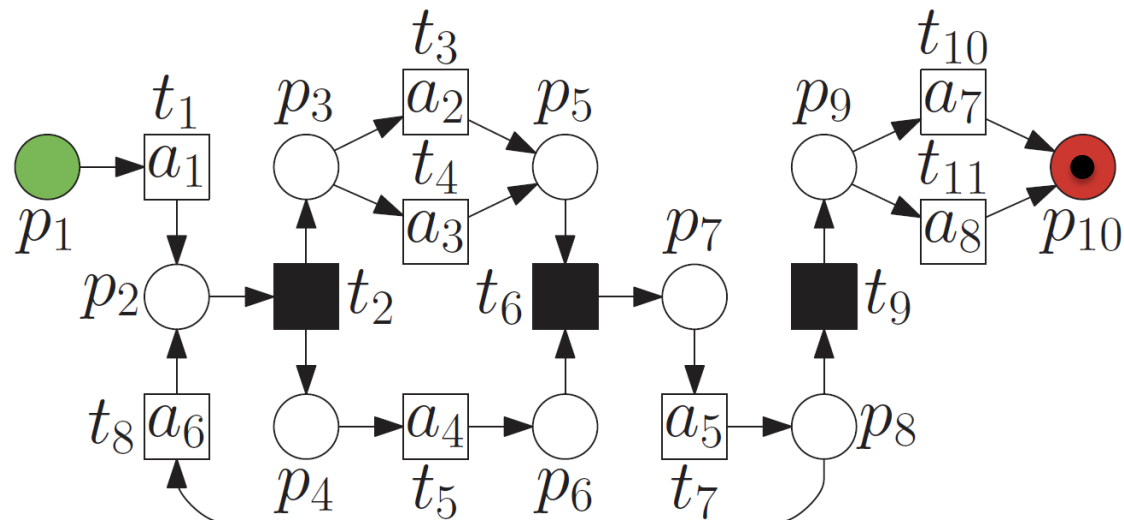
a_1	τ	a_2	a_3
t_1	t_2	t_3	\gg
0	0	0	10

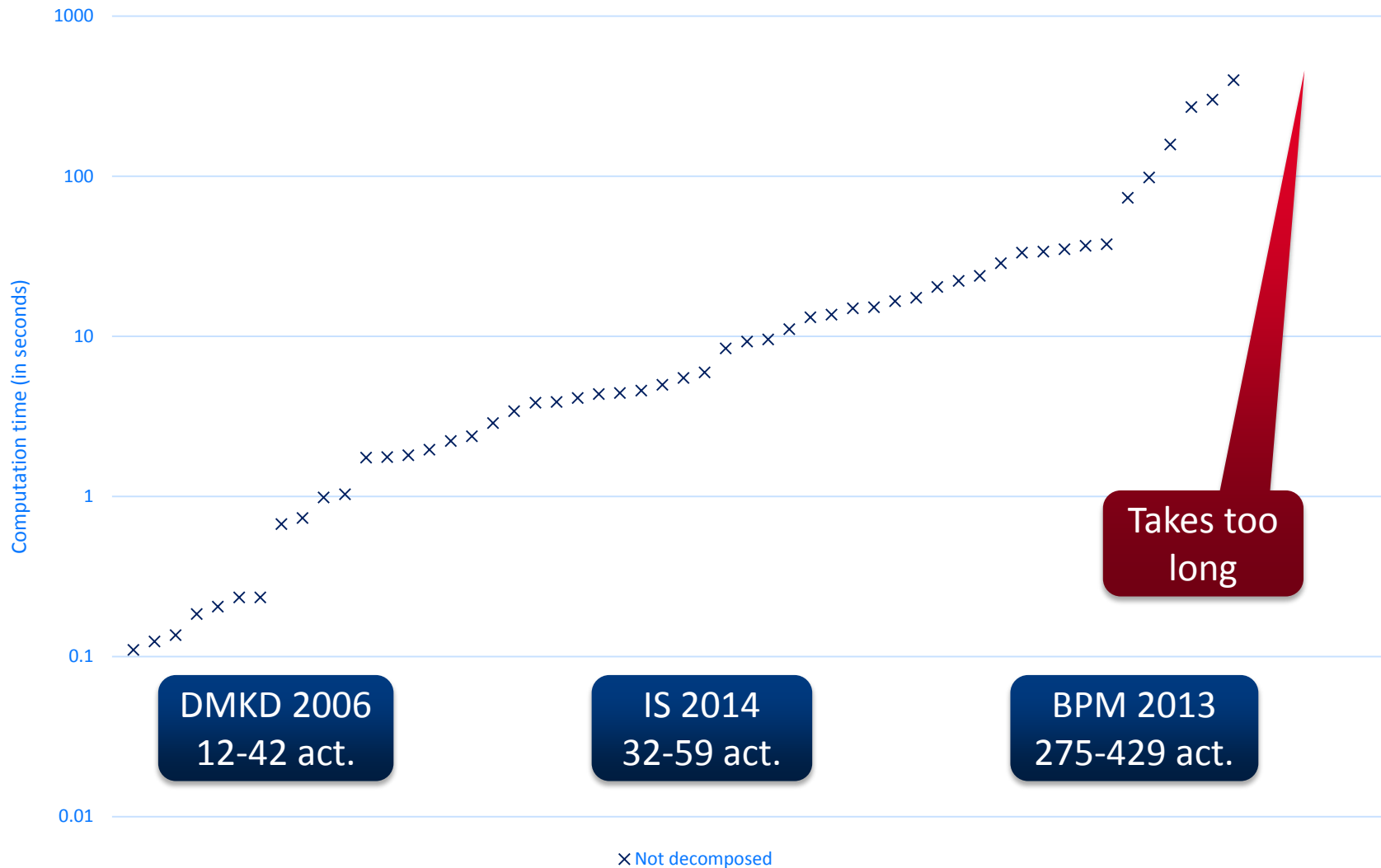
No match



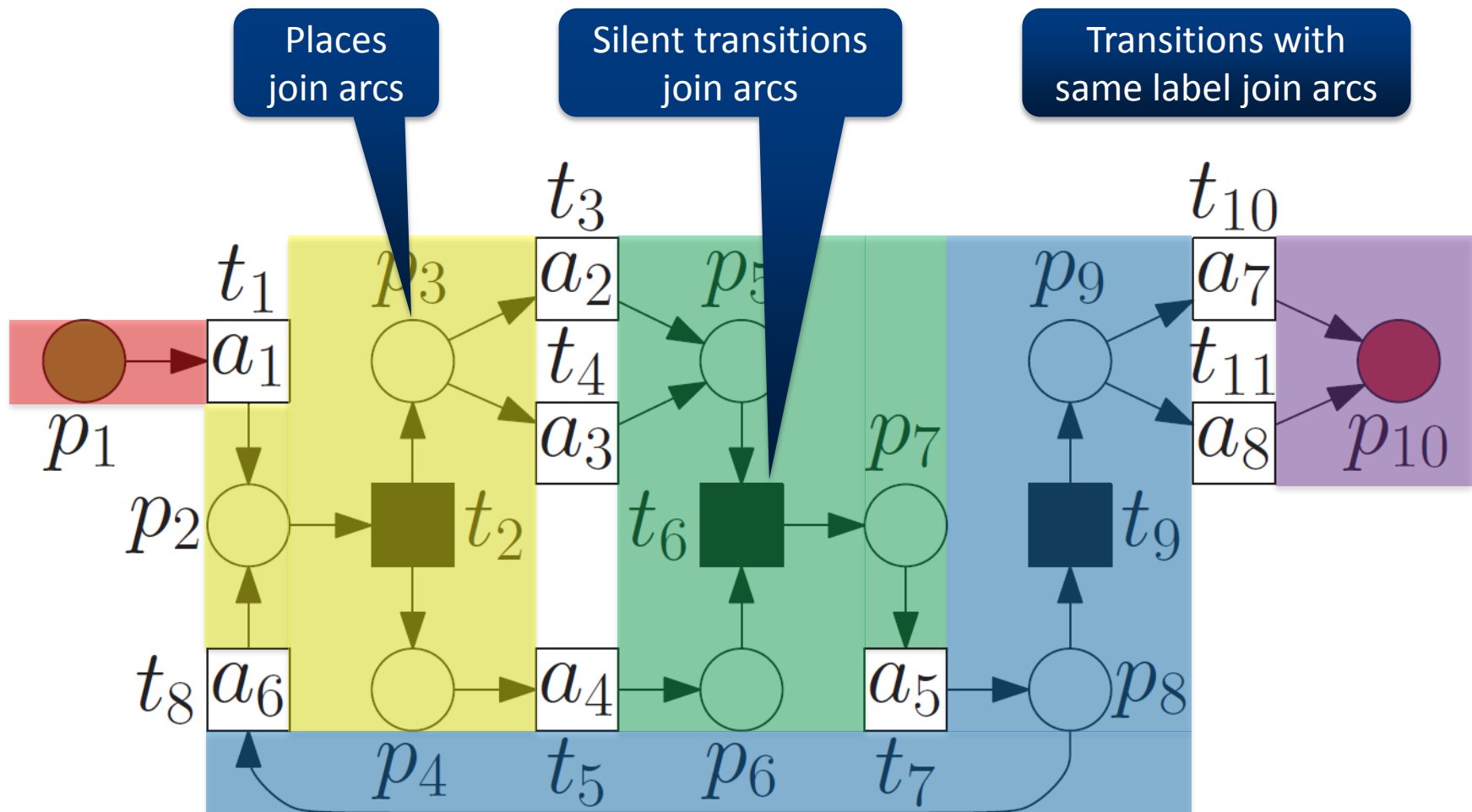
$$\langle a_1, a_2, a_3, a_4, a_5, a_6, a_7, a_8 \rangle$$

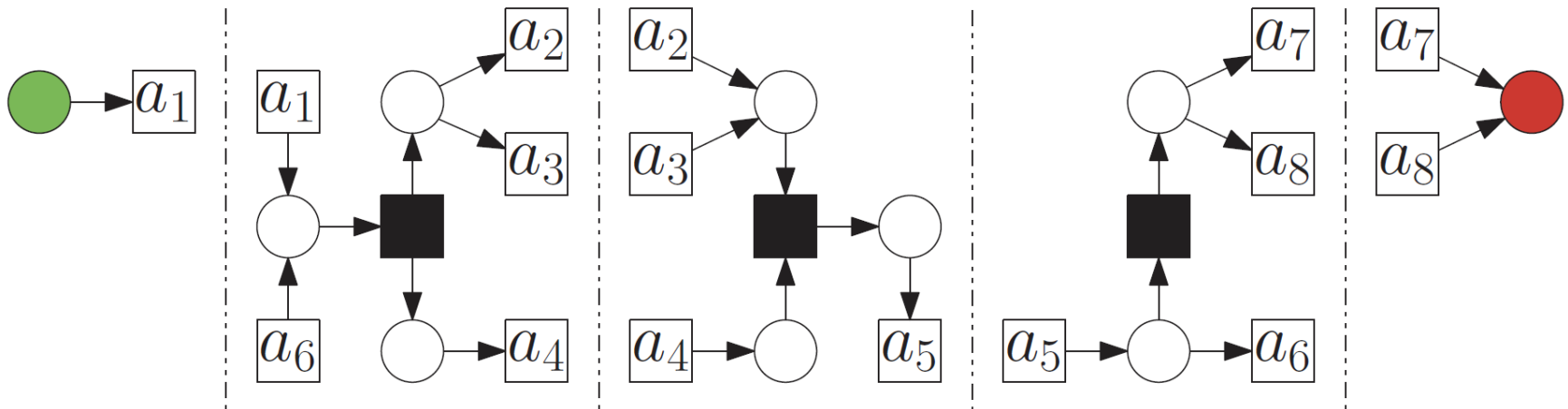
a_1	τ	a_2	a_3	a_4	τ	a_5	a_6	τ	a_7	a_8
t_1	t_2	t_3	\gg	t_5	t_6	t_7	\gg	t_9	t_{10}	\gg
0	0	0	10	0	0	0	10	0	0	10





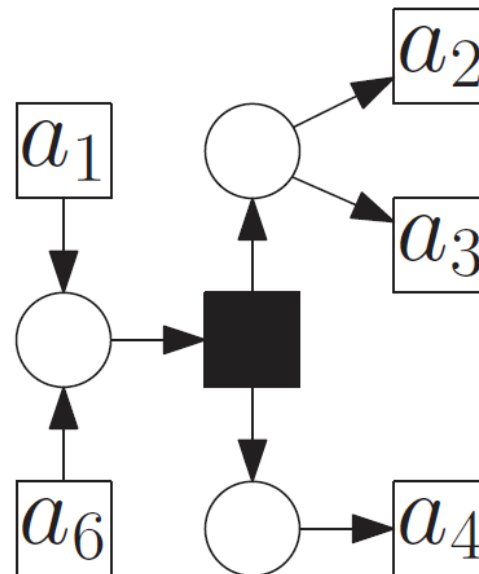
- Preliminaries
 - Monolithical replay
 - Decomposed replay
- Merging alignments
 - Pseudo alignment
 - Alignment of alignments
 - Stitching rules
- Wrapping up
 - Conclusions
 - Future work





$$\langle a_1, a_2, a_3, a_4, a_6 \rangle$$

a_1	τ	a_2	a_3	a_4	a_6
t_1	t_2	t_3	\gg	t_5	\gg
0	0	0	5	0	5

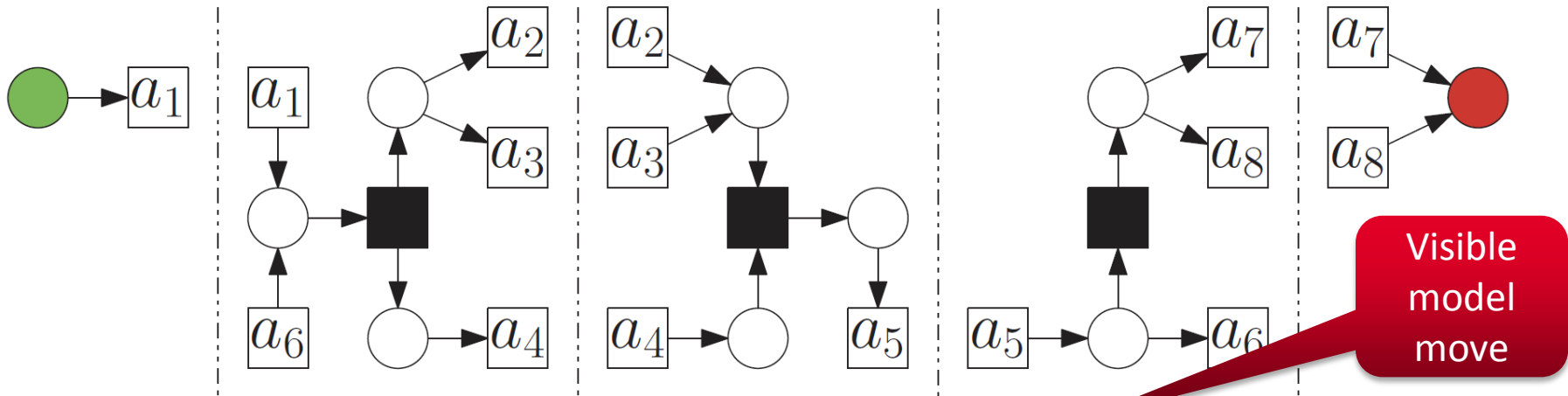


Adapted
costs

a_1
t_1
0

a_2	a_3	a_4	τ	a_5
\gg	t_4	t_5	t_6	t_7
5	0	0	0	0

a_7	a_8
t_{10}	\gg
0	5



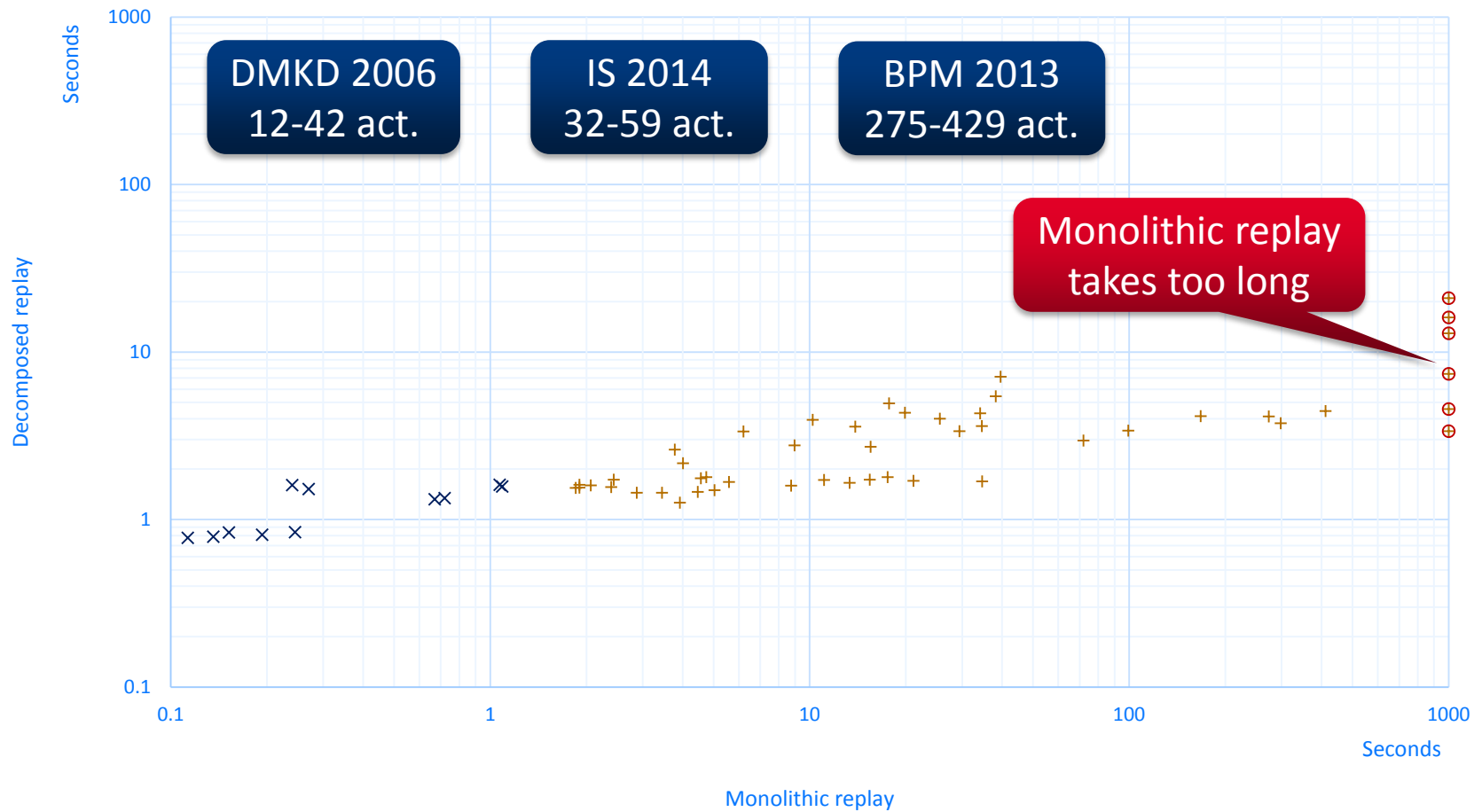
a_1	τ	a_2	a_3	a_4	a_6
t_1	t_2	t_3	\gg	t_5	\gg
0	0	0	5	0	5

a_5	a_6	\gg	τ	a_7	a_8
t_7	t_8	t_7	t_9	t_{10}	\gg
0	0	2	0	0	5

Visible
model
move

- Non-decomposed costs 0 **if and only** if decomposed costs 0
- Decomposed costs **less or equal** to non-decomposed costs

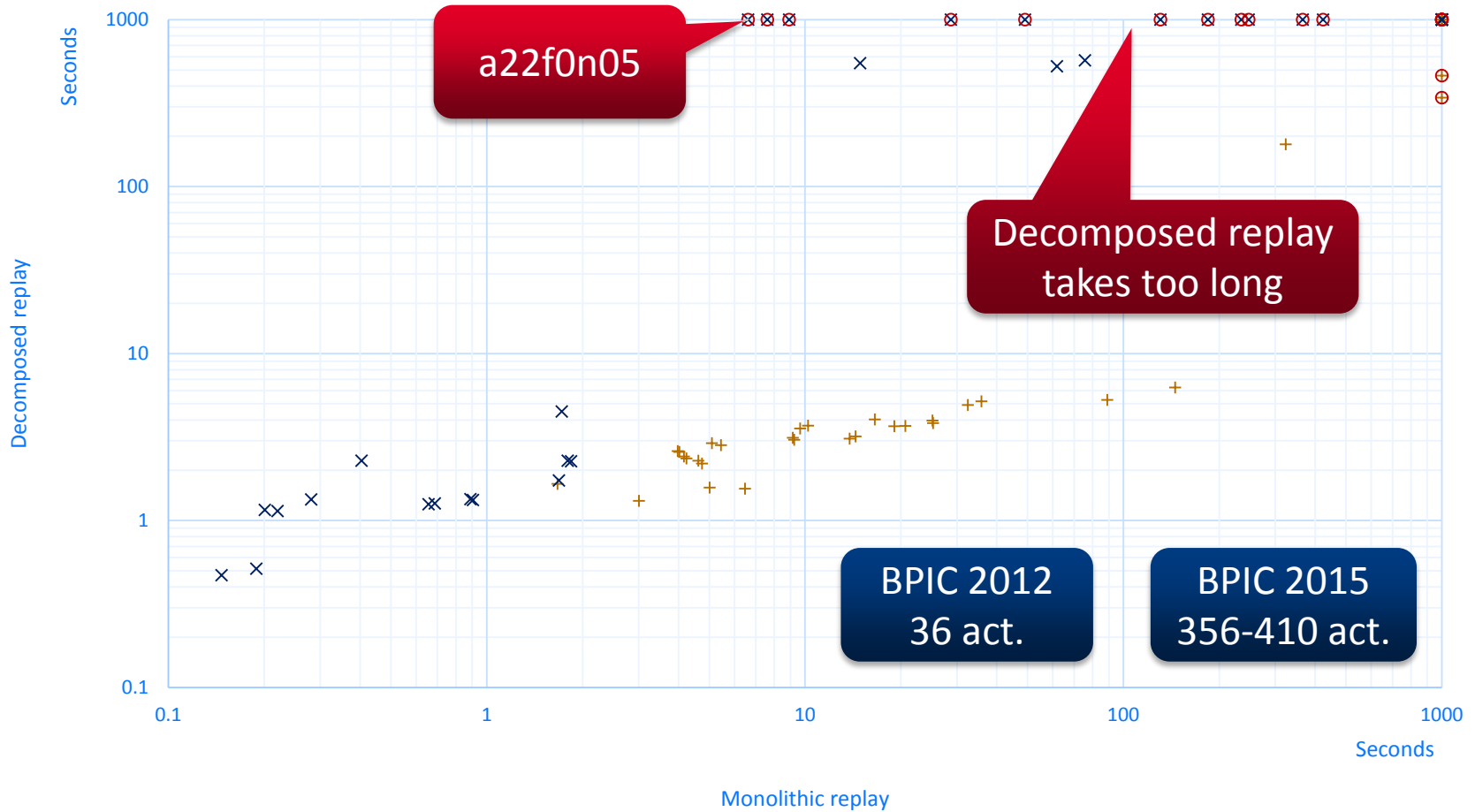
Computation times, with provided nets



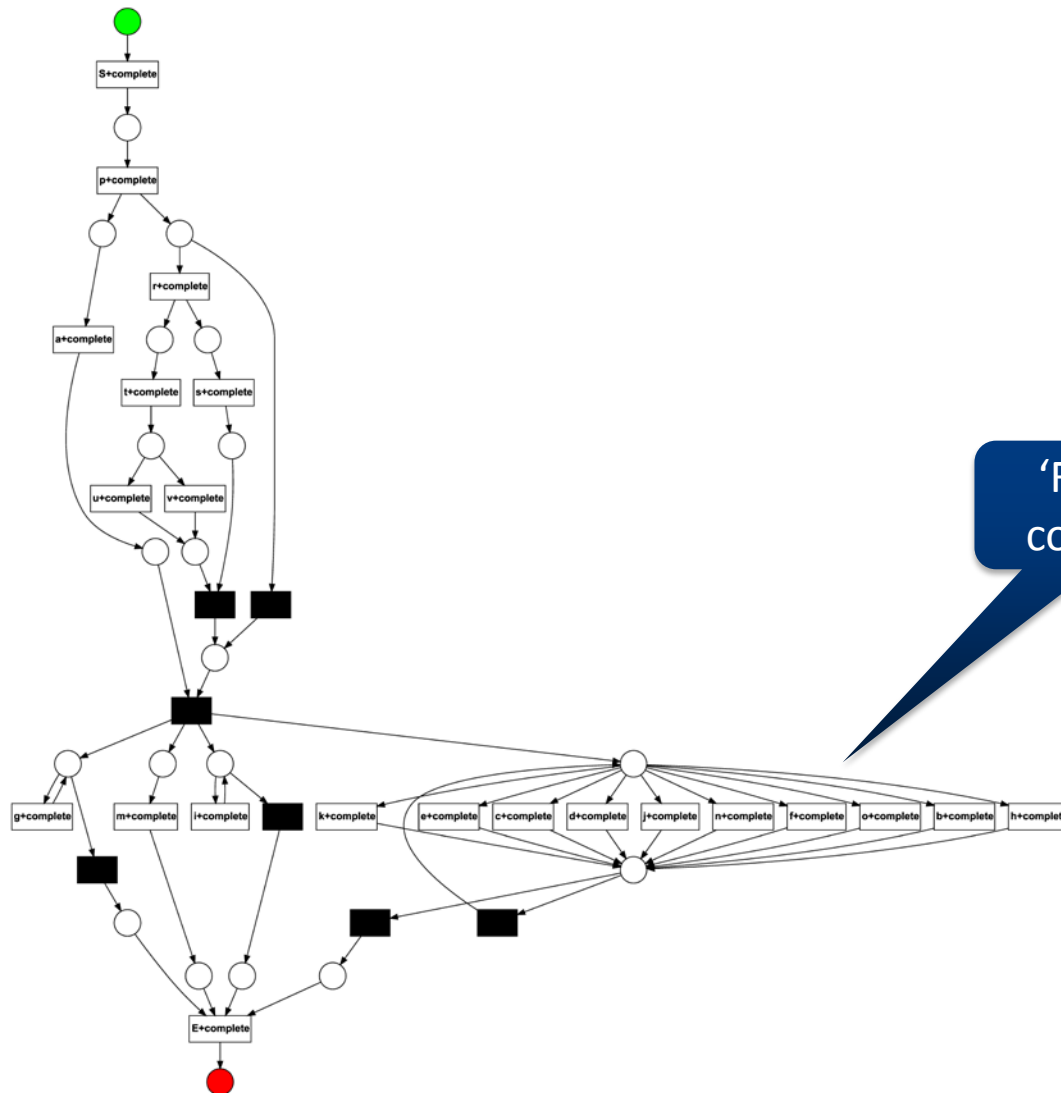
+ Decomposed replay is faster x Decomposed replay is slower o Infeasible

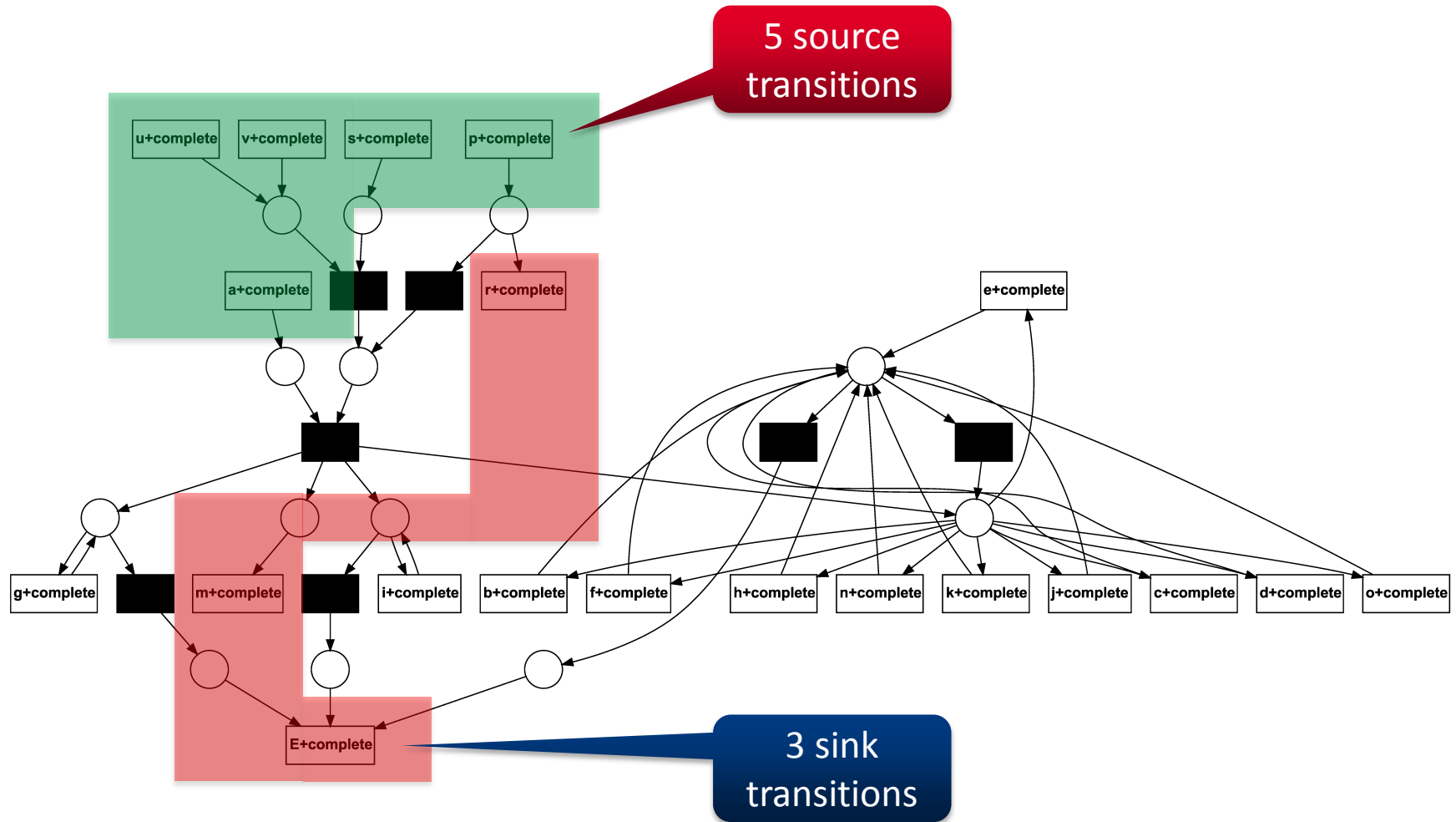
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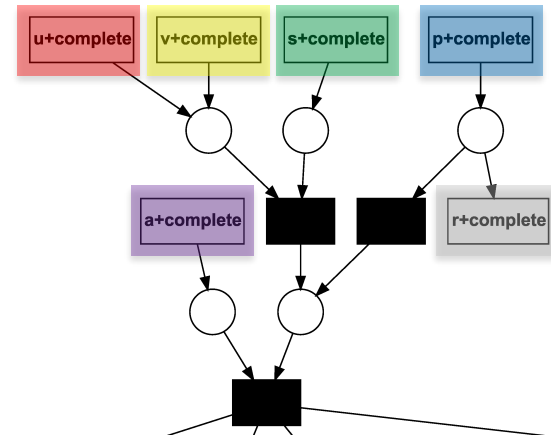
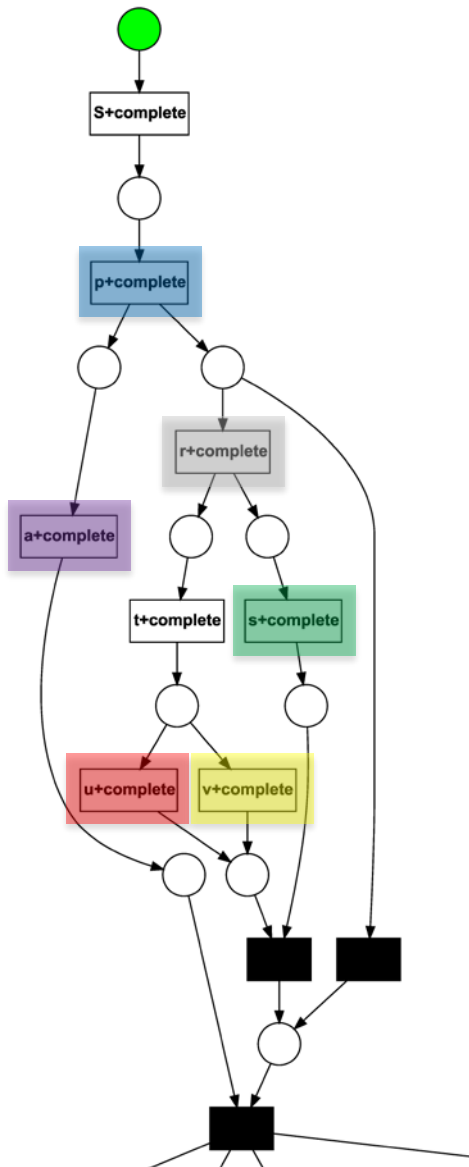
Computation times, with discovered nets



+ Decomposed replay is faster x Decomposed replay is slower o Infeasible

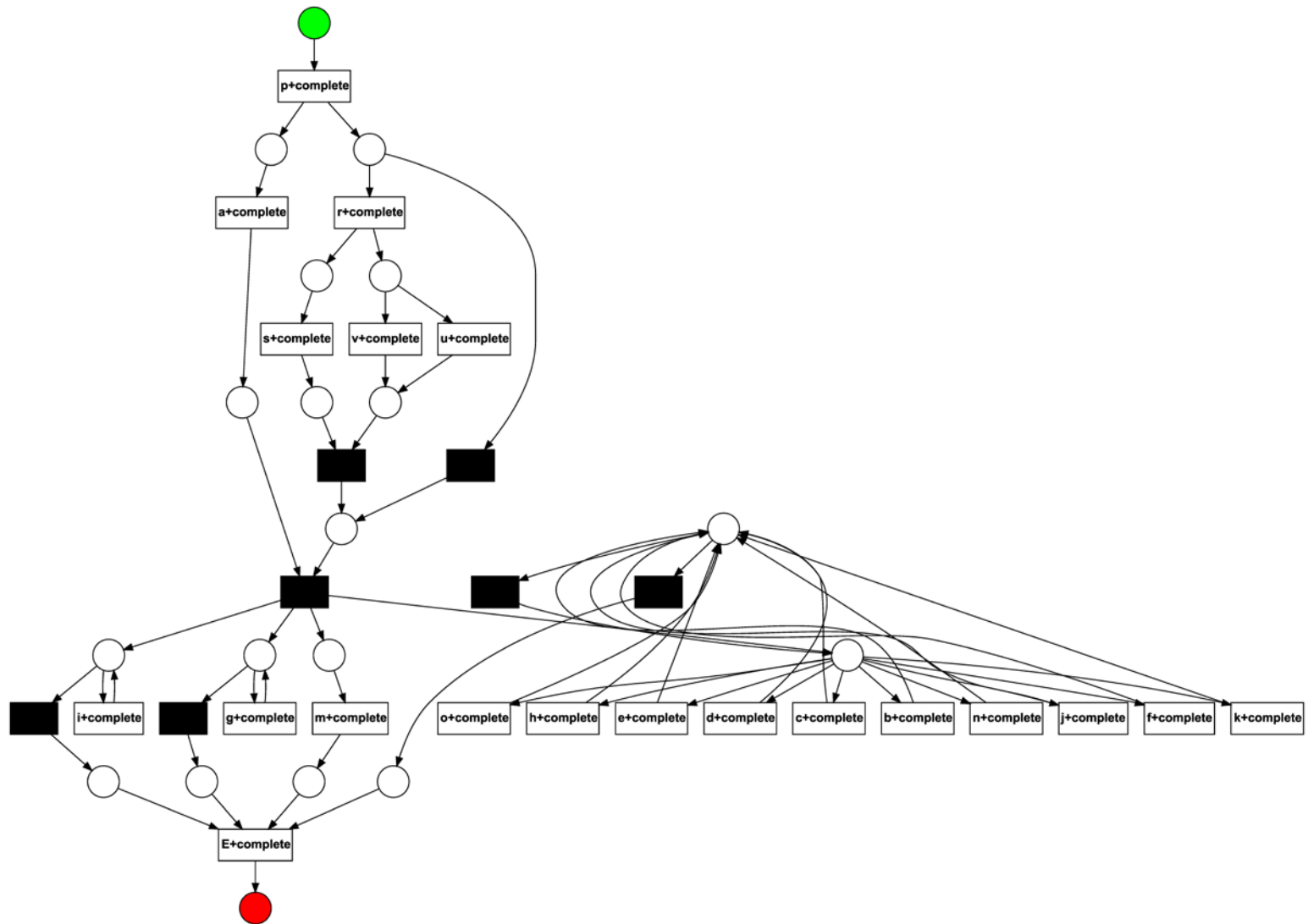


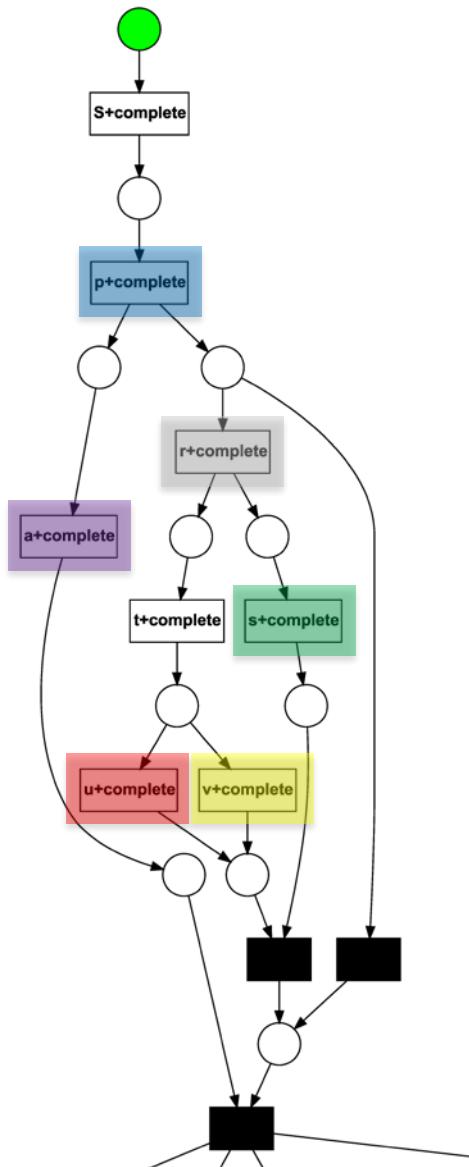




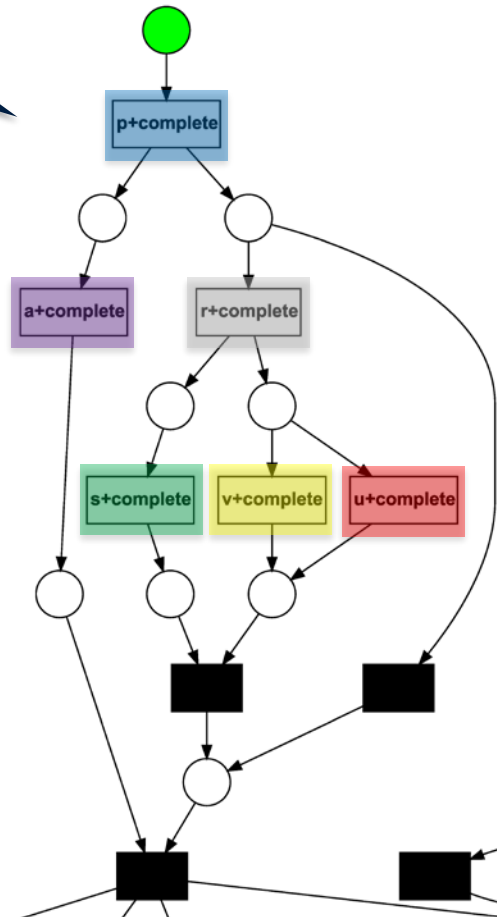
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- Hide visible transition ‘not covered’ by subnet
- Apply behavior-preserving reduction rules afterwards

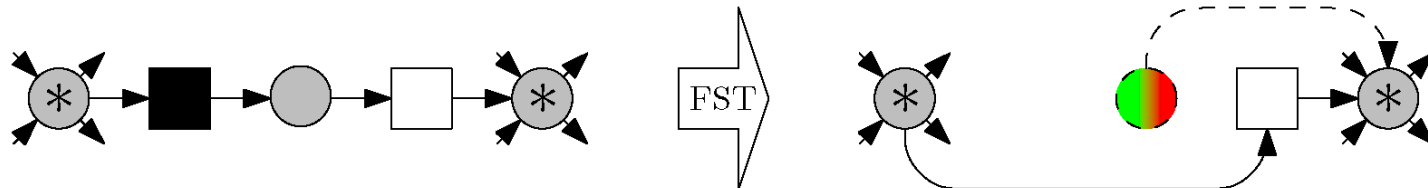
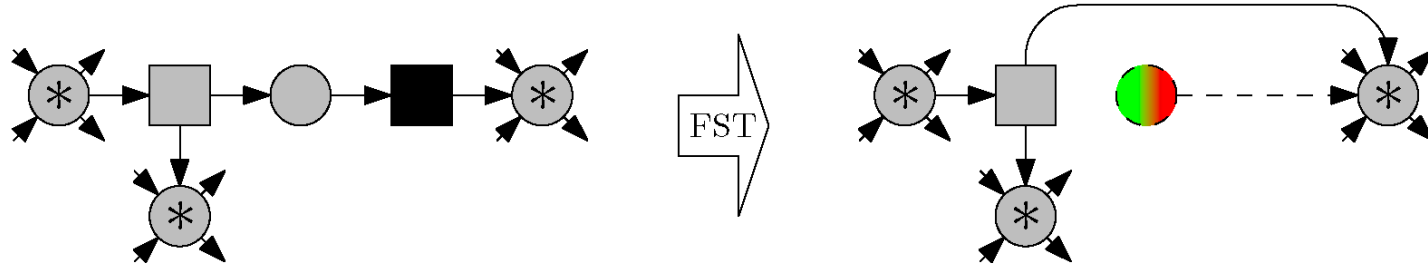




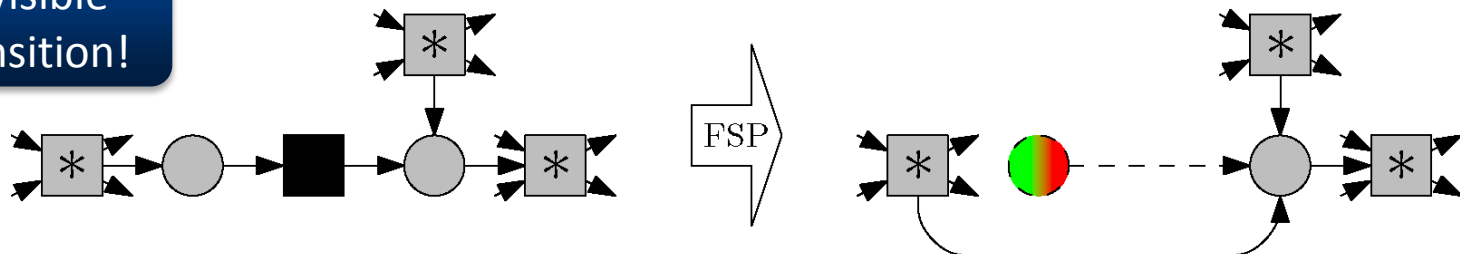
No source
transitions










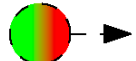
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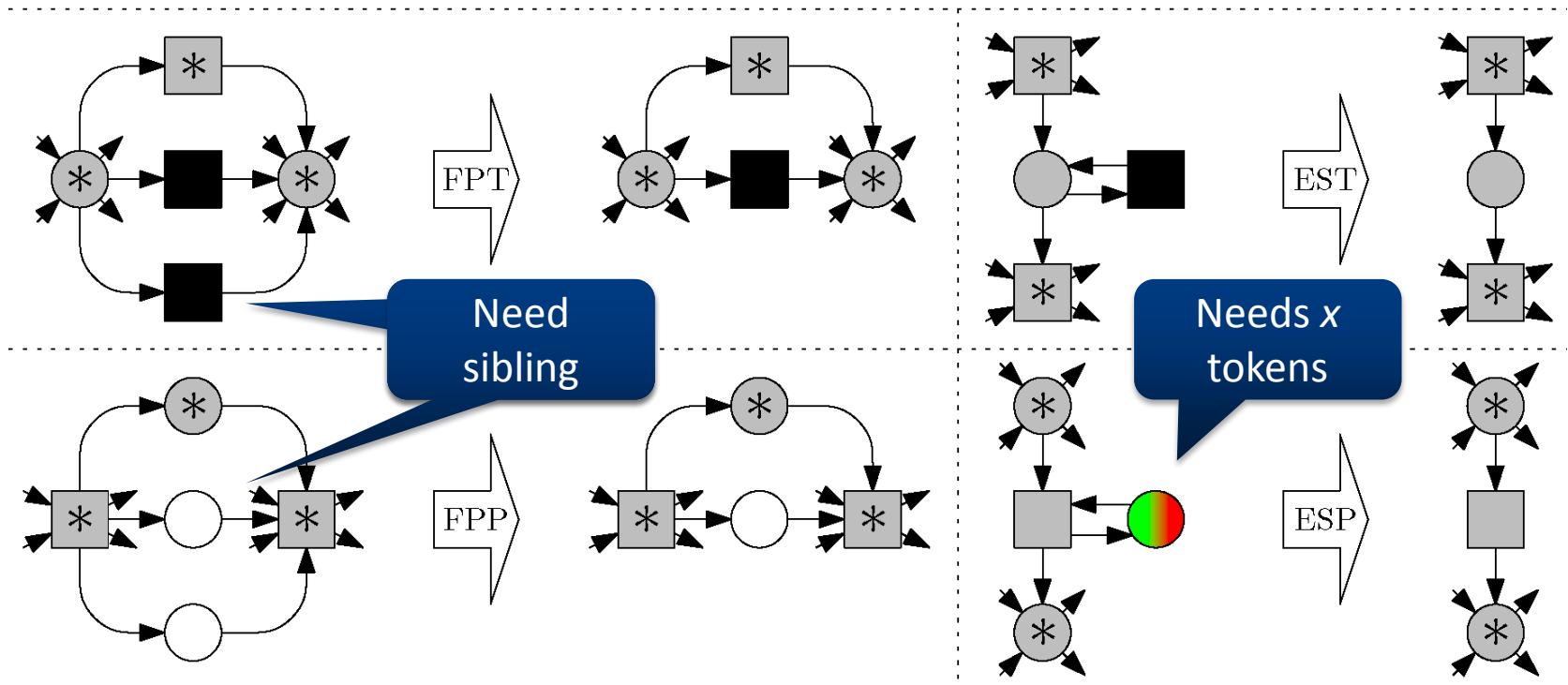


Invisible
transition!












Legend

	an invisible transition		a place containing x tokens in the initial and every final marking (where $x > 0$)	
	a visible transition		an unmarked place	 any number of these objects (includes connected arcs)
	any transition		any place	 updating initial and final markings if needed

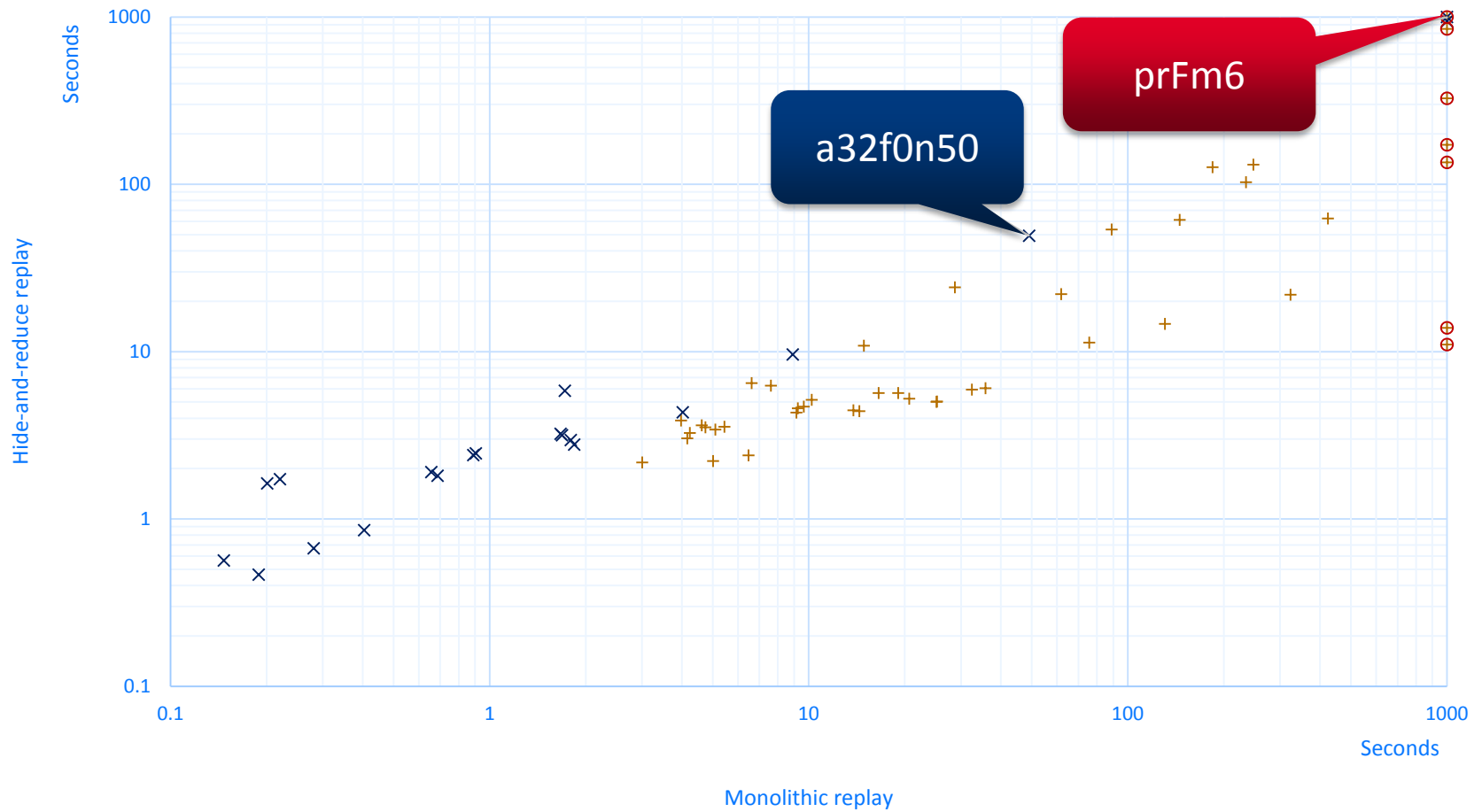


Legend

	an invisible transition		a place containing x tokens in the initial and every final marking (where $x > 0$)		any number of these objects (includes connected arcs)
	a visible transition		an unmarked place		any number of these objects (includes connected arcs)
	any transition		any place		updating initial and final markings if needed

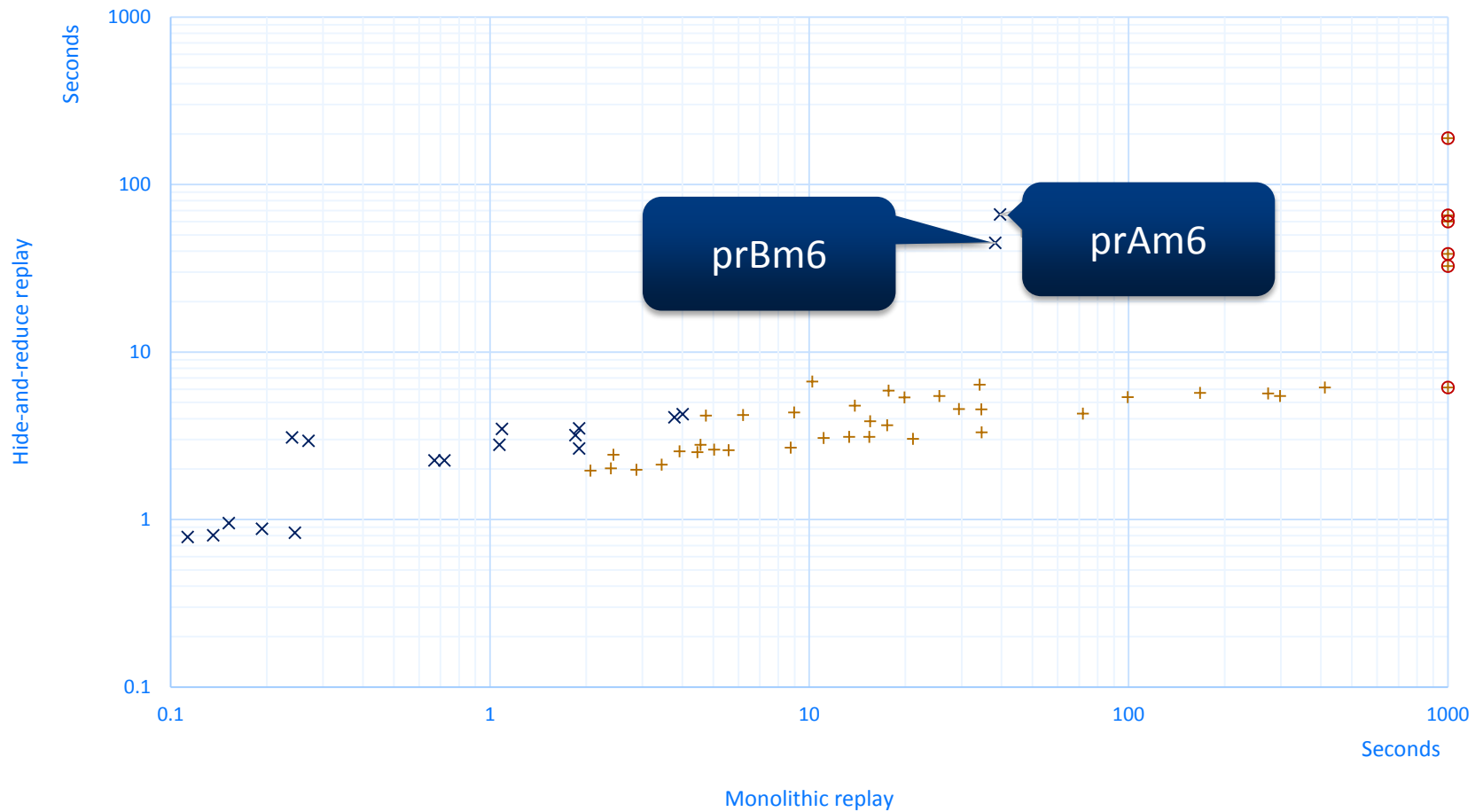
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Computation times, with discovered nets



+ Hide-and-reduce replay is faster x Hide-and-reduce replay is slower o Infeasible

Computation times, with provided nets



+ Hide-and-reduce replay is faster x Hide-and-reduce replay is slower o Infeasible

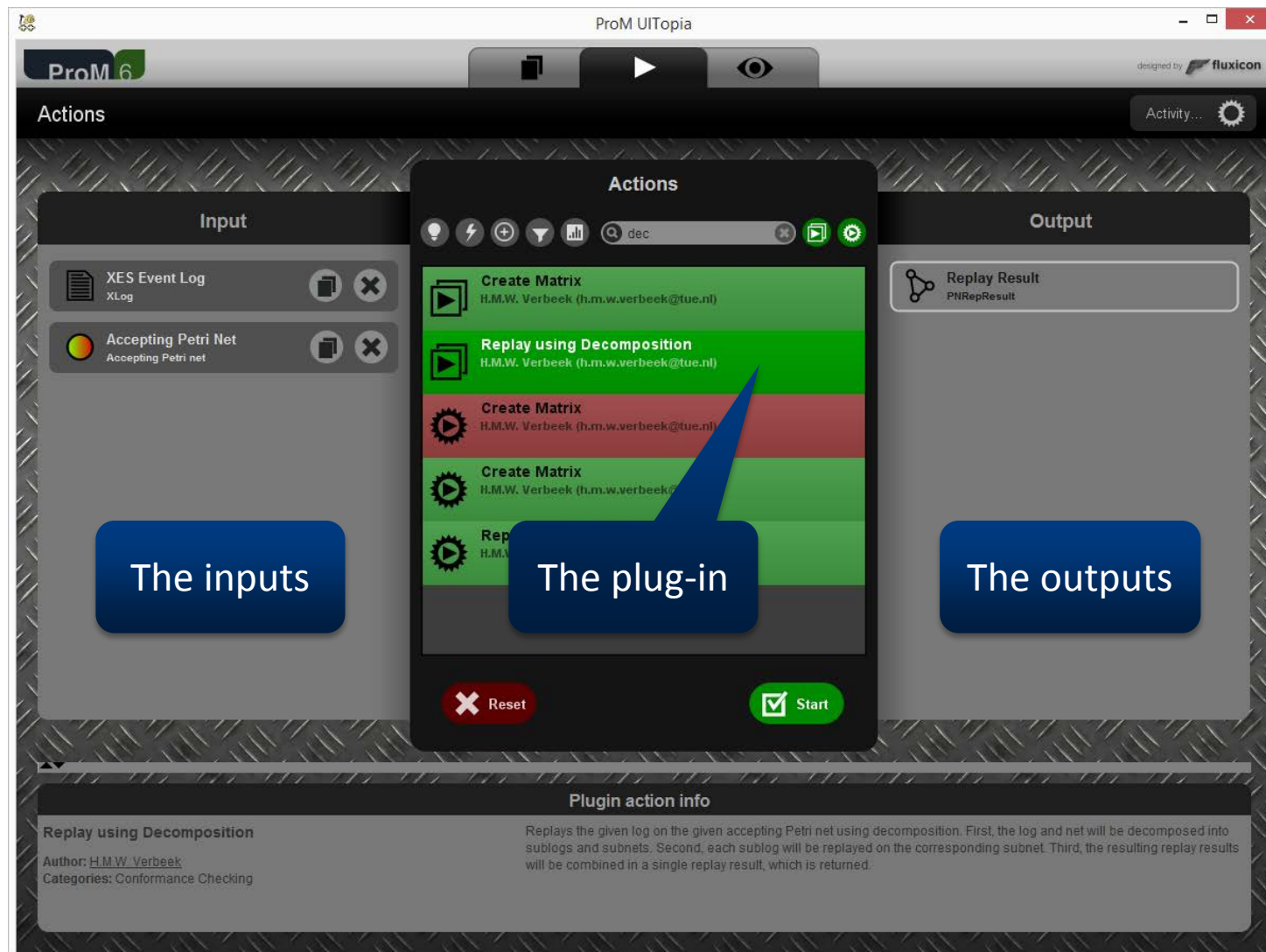
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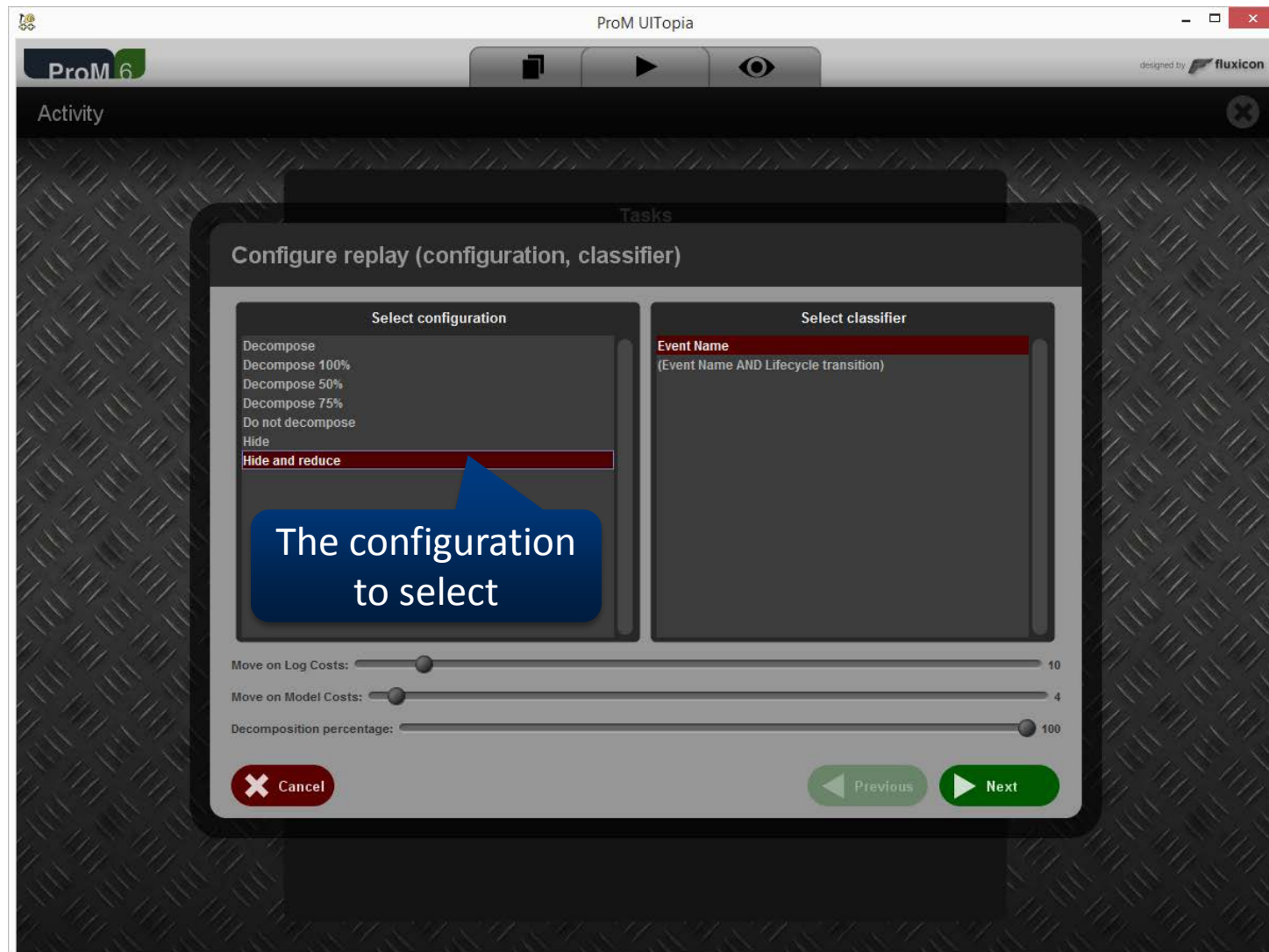
- Decomposed replay sometimes much worse
 - On discovered nets
 - From less than 10 seconds to more than 1000 seconds
- Hide&Reduce replay never much worse
 - On discovered or provided nets
 - Typically faster if it takes more than 10 seconds
 - From more than 1000 seconds to just above 10 seconds
- On provided nets
 - Decomposed replay
 - as it is fastest
- On discovered nets
 - Hide&Reduce replay
 - as it provides the most answers in 1000 seconds

Prom

Revision 28643

6.6





- Preliminaries
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- **Cost-preserving** reduction rules
 - Any reduction rule is fine, as long as it preserves the costs for any possible trace
 - Behavior-preserving implies cost-preserving, but might not equal
 - More rules?
 - Leading to better reduction?

Questions?